

Problems p. 305 #2, p. 313, # 11, 13

Recall: A congruence transformation

is: $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$, s.t.

1.) f is 1-1

2.) f is "distance preserving" (isometry)

$$d(f(P), f(Q)) = d(P, Q)$$



$d = \text{Euclidean dist.}$ $d((x, y), (x', y')) = \sqrt{(x-x')^2 + (y-y')^2}$

Today: Some examples of congruence transformations

a) synthetic b) analytic (\mathbb{R}^2) c) analytic (\mathbb{C})

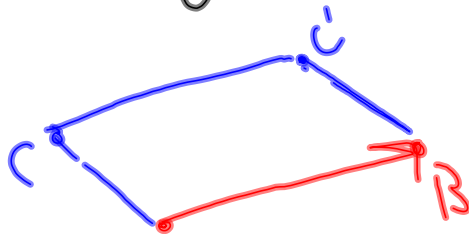
* Translations

a) Let \vec{AB} be a directed line segment.

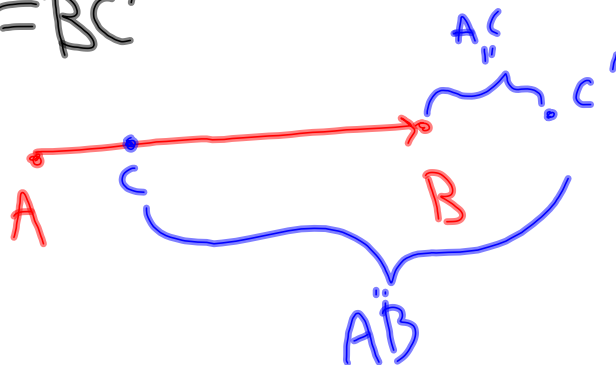
$T_{\vec{AB}}$ = translation along \vec{AB}

$T_{\vec{AB}}(C) \stackrel{\text{def}}{=} C'$, where

i) If C is not on \vec{AB} , then
 C' = the unique point s.t. $ABCC'$
is a parallelogram:



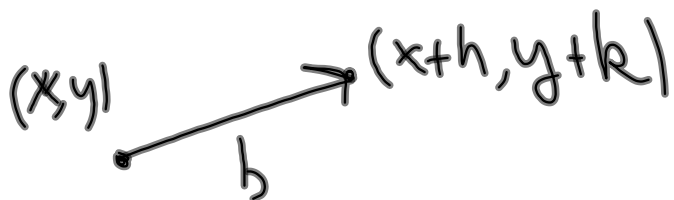
ii) If C lies on \vec{AB} , then
 C' = unique point s.t. $AB = CC'$
and $AC = BC'$



b) Let b = the vector in \mathbb{R}^2 rep'd
by $\vec{AB} = (h, k)$

Translation along $\vec{AB} \leftrightarrow$ addition of b

$$T_b(x, y) = (x + h, y + k)$$



Rems: • $T_0(x, y) = (x, y), \quad \forall x, y$

so $T_0 = \text{id}$ (identity transformation of \mathbb{R}^2)

• Can compose translations:

$$\begin{aligned} T_{b_2} \circ T_{b_1}(x, y) &= T_{b_2}(x+h_1, y+k_1) \\ \underbrace{(h_2, k_2)}_{b_2} \quad \underbrace{(h_1, k_1)}_{b_1} &= (x+h_1+h_2, y+k_1+k_2) \\ &= T_{b_1+b_2}(x, y) = T_{b_1} \circ T_{b_2}(x, y) \end{aligned}$$

so $T_b \circ T_{-b} = T_0 = \text{id}$

$$\mathbb{T} = \left\{ \begin{array}{l} \text{translations of } \mathbb{R}^2 \\ \tau: \mathbb{R}^2 \rightarrow \mathbb{R}^2 \end{array} \right\}$$

= a commutative group under composition of translations.

Moreover, the map

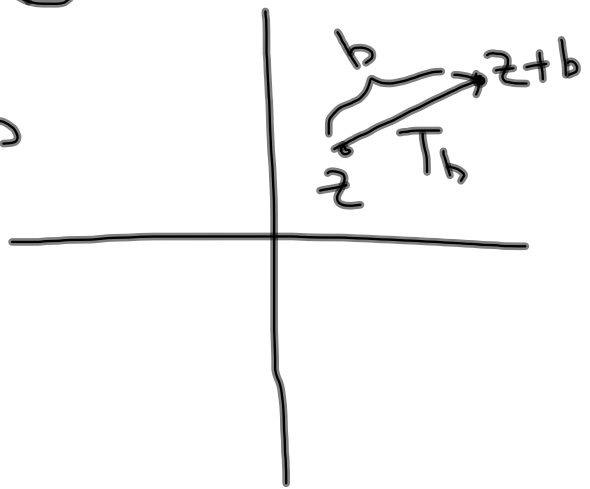
$$\begin{array}{ccc}
 (\mathbb{R}^2, +) & \xrightarrow{\quad} & (\mathbb{T}, \circ) \\
 \cup & & \uparrow \text{composition} \\
 \mathbb{R} & \xrightarrow{\quad} & \mathbb{T}_b
 \end{array}$$

is an isomorphism of groups.

$$c) \quad b = h + ik \in \mathbb{C}$$

$$T_b(z) = z + b$$

$\underset{\substack{= \\ x+iy}}{\quad}$



Thm: For all $b \in \mathbb{C}$,
 T_b is an isometry.

pf: $|T_b(z) - T_b(w)| = |(z+b) - (w+b)| = |z-w|$

Rotations:

a) C a point in the plane,
 $\phi =$ a real number (radians)
 $-\pi < \phi \leq \pi$

$R_{C,\phi} :=$ rotation through angle of ϕ
with center C .

- $R_{C,\phi}(C) = C$

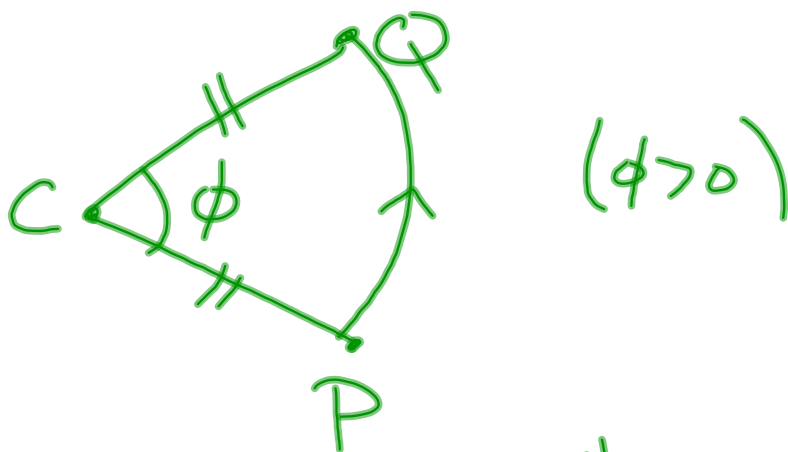
$P \neq C$ • $R_{C,\phi}(P) = Q$, for Q
the unique point satisfying

i) $PC = QC$

ii) $m\angle PCQ = |\phi|$

• $\triangle PCQ$ oriented $\begin{matrix} \text{CCW if } \phi > 0 \\ \text{CW if } \phi < 0 \end{matrix}$

* $R_{C,0} = \text{id}$.



* Can generalize to allow any ϕ .

If $\phi \equiv \phi' \pmod{2\pi\mathbb{Z}}$, then

$$\phi - \phi' = 2\pi \cdot n, n \in \mathbb{Z}$$

$$R_{C,\phi} = R_{C,\phi'}$$

Can compose rotations

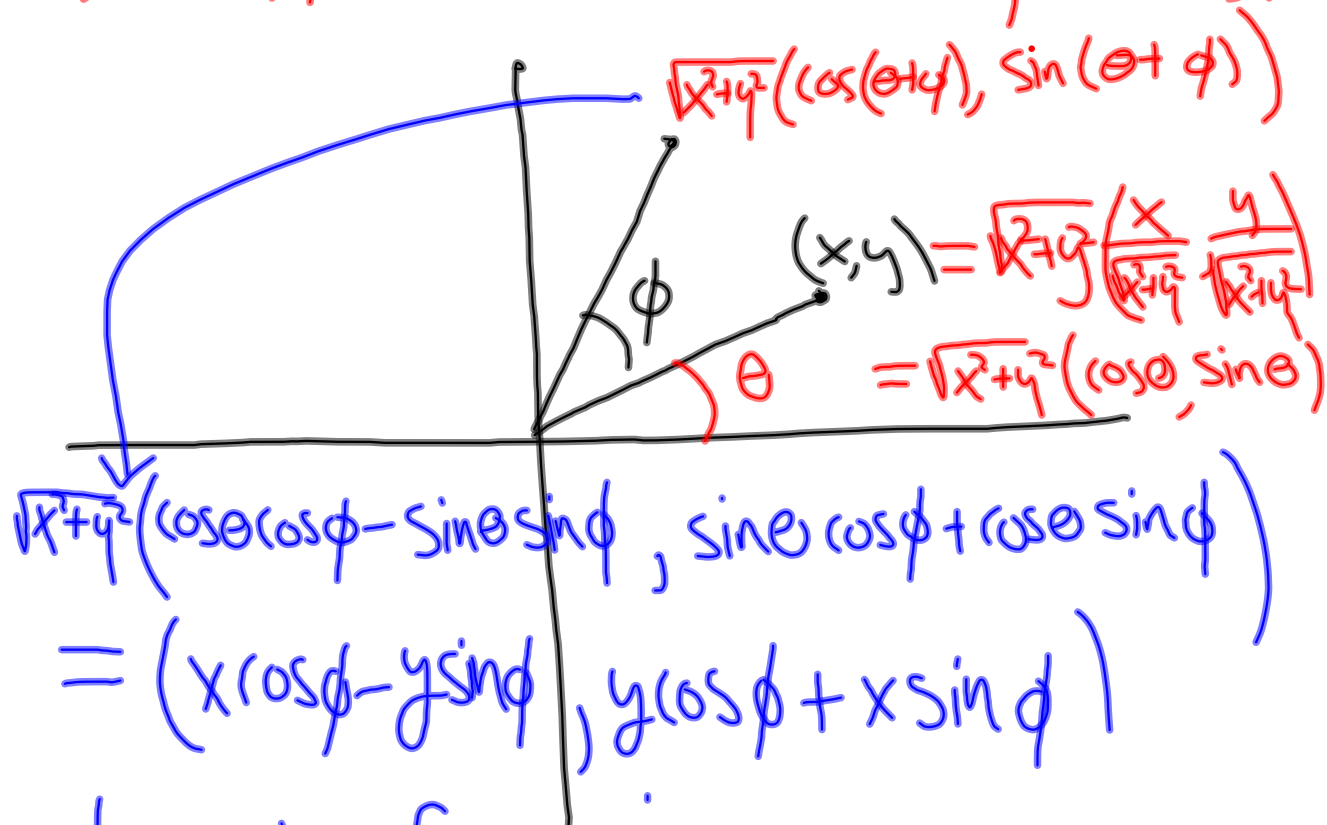
$$R_{C, \phi_2} \circ R_{C, \phi_1} = R_{C, \phi_1 + \phi_2}$$

$R_{C, 0} = \text{id}$, so we get

$$\mathbb{R} / 2\pi\mathbb{Z} = \left\{ \begin{array}{l} \text{the group} \\ \text{of reals} \\ \text{mod } 2\pi\mathbb{Z} \\ \text{under } + \end{array} \right\} \xrightarrow{\phi \mapsto R_{C, \phi}} \left\{ \begin{array}{l} \text{rotations} \\ \text{about } C, \\ \text{under } \circ \end{array} \right\}$$

is a group isomorphism.

b) Suppose $C = \text{origin}$, $R_\phi := R_{C, \phi}$



In matrix form

$$[R_\phi] = \begin{bmatrix} \cos\phi & -\sin\phi \\ \sin\phi & \cos\phi \end{bmatrix}$$

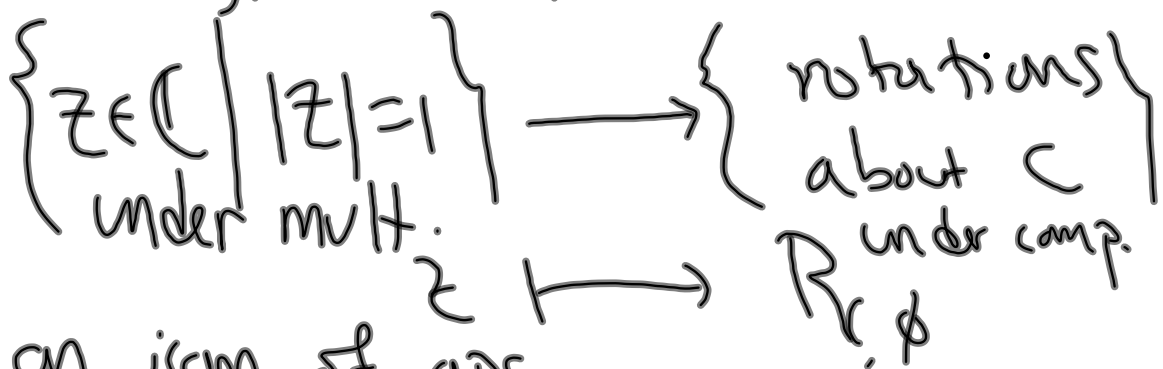
More generally

$$R_{c, \phi} = T_c \circ R_\phi \circ T_{-c}$$

$$\begin{aligned} c) \quad R_\phi(x+iy) &= (x \cos \phi - y \sin \phi) \\ &\quad + i(x \sin \phi + y \cos \phi) \\ &= (x+iy) \underbrace{(\cos \phi + i \sin \phi)}_{z_\phi = e^{i\phi}} \end{aligned}$$

Hence

$$R_{c, \phi}(z) = z_\phi(z-c) + c$$



is an isom. of gps.

Ex prove $R_{c, \phi}$ is an isometry.

