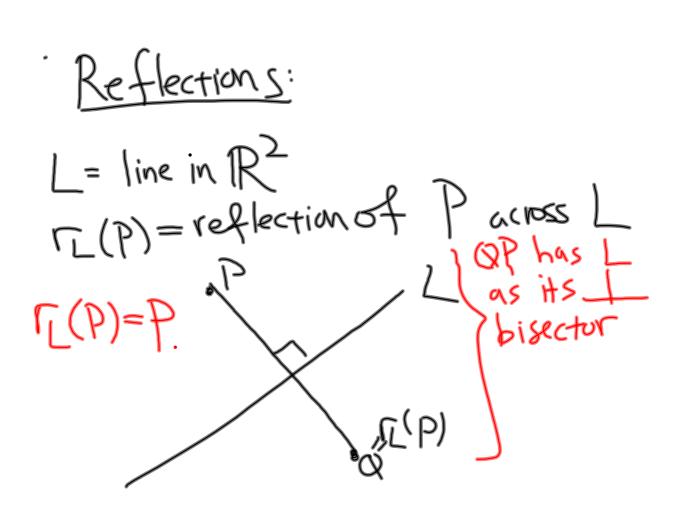
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$$3 \text{ special (ases} \qquad P = (x,y)$$

$$1) L = x \text{-axis} \qquad x \text{-axis}$$

$$[x \text{-axis}] = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \qquad x \text{-axis} (P) = (x,-y)$$

$$2) L = y \text{-axis} (-x,-y)$$

$$[x \text{-axis}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$3) L = \text{line } y = x$$

$$[x \text{-axis}] = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad P = (x,y)$$

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Let's figure at a formula for Ty = reflection across Ly Inick: Rotate coordinate axes! $R_{-\phi} = r_{x} \cdot R_{-\phi}$ So $R_{\phi} \circ R_{\phi} \circ \Gamma_{\phi} = R_{\phi} \circ \Gamma_{x} \circ R_{-\phi}$

Monday:
$$[R_{\phi}] = [\cos \phi - \sin \phi]$$

 $[\sin \phi \cos \phi]$

$$\begin{bmatrix} \Gamma_{ij} \end{bmatrix} = \begin{bmatrix} R_{ij} \circ \Gamma_{x} \circ R_{-ij} \end{bmatrix} = \begin{bmatrix} R_{ij} & \Gamma_{x} & R_{-ij} \end{bmatrix}$$
$$= \begin{bmatrix} r \circ s d & -s in d \\ sin d & cos d \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} cos d & s in d \\ -s in d & cos d \end{bmatrix}$$
$$= \begin{bmatrix} r \circ s d & -s in d \\ sin d & (cos d) \end{bmatrix} \begin{bmatrix} cos d & s in d \\ sin d & -(cos d) \end{bmatrix}$$
$$\begin{bmatrix} cos^{2} d - s in^{2} d \\ cos d s in d & -(cos^{2} d - s in^{2} d) \end{bmatrix} \begin{bmatrix} cos 2 d & s in 2d \\ sin 2d & -(cos^{2} d - s in^{2} d) \end{bmatrix} \begin{bmatrix} cos 2 d & s in 2d \\ sin 2d & -(cos^{2} d - s in^{2} d) \end{bmatrix} \begin{bmatrix} cos 2d & s in 2d \\ sin 2d & -(cos^{2} d - s in^{2} d) \end{bmatrix} \begin{bmatrix} cos 2d & s in 2d \\ sin 2d & -(cos^{2} d - s in^{2} d) \end{bmatrix} \begin{bmatrix} cos 2d & s in 2d \\ sin 2d & -(cos^{2} d - s in^{2} d) \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin 2d & -r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & -r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & -r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & -r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & -r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & -r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - r - s r d \\ sin r d & r - s r d \end{bmatrix} \begin{bmatrix} r - r - s r - s r d \\ sin r d & r - s r$$

In porticular: I) [(x,y)= (xrosz¢tysinz¢, xsin 2¢ -ycosz¢) 2) $\Gamma_{q} r_{\chi} = R_{2q} r_{\chi} r_{\chi} = R$ VZØ $\Gamma_{\phi_2} \Gamma_{\phi_1} = \widehat{k}$ (orollary.) 2($\phi_2 - \phi_1$) Eg R2(\$2-9,1)

Complex picture Complex conjugation $\mathcal{R}(z) := \overline{z} = a - bi, where z = a$ =atbi 1 X axis Last time: R_{f} (onesponds to multiply $Z_{f}:=(os\phi+isin\phi=e^{i\phi})$ SO: $\Gamma_{f}=R_{2\phi}r_{X}$, i.e. $\Gamma_{L}(z)=Z_{2\phi}z_{F}$

tor a general line (maybe not (antuining angin) $E_{,\phi} = Z_{2\phi}(z-c) + c$ where repeated in arrows line through a that forms an angle of \$ c for reflection across this line M X-axis. Using this, can show that $\mathcal{L}_{2,\phi} \circ \mathcal{L}_{1,\phi} = \mathcal{Z} + \{\text{something}\}$ = translation