

Generalized Local Induction, Hasimoto's Map and Admissible Vortex Geometries

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Outline

A Few Words Before We Begin

If they understand the problem then you have done something.

Binormal Flow of a Vortex Filament

Vorticity $\omega = \nabla \times \mathbf{v}$ where $\omega, \mathbf{v} : \mathbb{R}^{3+1} \rightarrow \mathbb{R}^3$

Vortex Filament Plane curve localization, $\omega \neq 0$ on $\xi : \mathbb{R} \rightarrow \mathbb{R}^3$

Self-Induced Motion Local evolution $\partial_t \xi = \kappa [\mathbf{T} \times \mathbf{T}' / |\mathbf{T}'|] = \kappa \mathbf{B}$

Binormal Flow and nonlinear PDE

Evolution of $\mathbf{Y} = A \mathbf{T} + Y \mathbf{T}'$ where $\mathbf{Y} = \mathbf{T} + \mathbf{B}$

Wave Equation $\partial_t^2 \mathbf{Y} = \partial_s^2 \mathbf{Y}$

Heat Equation $\partial_t \mathbf{Y} = \partial_s^2 \mathbf{Y}$

The Fundamental Problem

- What does the wave function's vortex look like?

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Evolution of $\mathbf{Y} = \mathbf{A} + \mathbf{Y} \cdot \mathbf{Y} \cdot \mathbf{Y} = \mathbf{T} \cdot \mathbf{T} \cdot \mathbf{B}$

Wave Equation

Heat Equation $\partial_t \mathbf{Y} = \mathbf{B}$

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$\partial_t \mathbf{v} = \nabla \times (\mathbf{v} \times \boldsymbol{\omega}) - \nabla (\mathbf{v} \cdot \nabla \mathbf{v}) + \nabla (\boldsymbol{\omega} \cdot \nabla \mathbf{v})$

or

$\partial_t \mathbf{v} = \nabla \times (\mathbf{v} \times \boldsymbol{\omega})$

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Serret-Frenet $\mathbf{Y}'_s = \mathbf{A}(\kappa_s, \tau_s) \mathbf{Y}_s$ where $\mathbf{Y}_s = [\mathbf{T} \ \mathbf{N} \ \mathbf{B}]^T$

A Wave Function $\psi = \kappa e^{i\Phi}$ where $\Phi = \int^s \tau ds'$

Hasimoto's NLS $\mathbf{M} = (\mathbf{N} + i\mathbf{B}) e^{i\Phi} \rightarrow i\partial_t \psi + \partial_{ss} \psi + \frac{1}{2} |\psi|^2 \psi = 0$

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Hydrodynamic Problems

Vortices: A strange love hate relationship

A Millennium Problem

A fundamental problem in analysis is to decide whether smooth, physically reasonable solutions exist for the Navier–Stokes equations.

Role of Vorticity

Vorticity acts as a defining source of fluid flow in the absence of boundary influence, a kind of internal 'skeleton' that determines the structure of the flow.

Finite time vortex blowup and energy cascade

Fluid turbulence is observed to contain small domains of very large vorticity.

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Rescued by the Superfluid

...or how learned to stop worrying and love the quanta.

Landau's two-fluid model (1941)

For temperatures

$0 < T < 2.172K = T_\lambda$, ^4He acts as if it were a mixture of two fluids,

$$\mathbf{v} = \mathbf{v}_n + \mathbf{v}_s, \quad (1)$$

where \mathbf{v}_n is a Navier-Stokes like fluid and \mathbf{v}_s is the superfluid component.

Lambda point transition

Superfluid Liquid Helium

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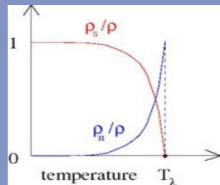
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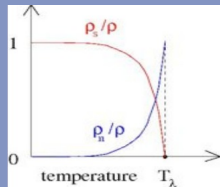
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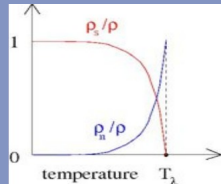
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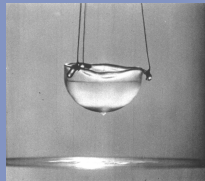
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Quantization of vortex core size

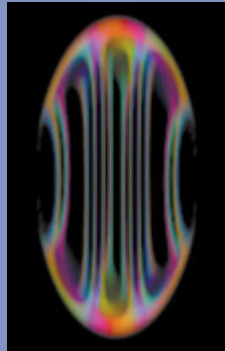
R. Feynman (1955)

Geometrically these nodal points must essentially form lines through the fluid. They are quantized vortex lines.

R. Donnelly (2001)

The rotating bucket contains a uniform array of N vortices with a 'vortex-free strip' on the outside having quantized circulation.

Simulated vortices in a Bose-Einstein condensate



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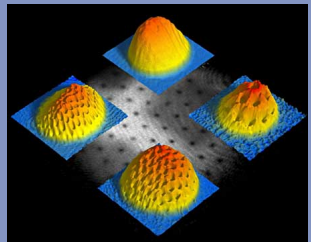
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Gustavson vortex lattice



Turbulent Tangles

As good as it gets.

Theory and experiment

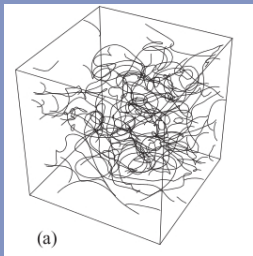
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Numerical tangle,
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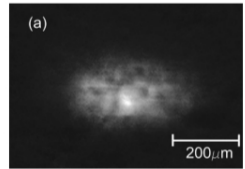
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(b)



Problem Statement

Hopes and Dreams

Fundamental Question: Redux

If vorticity is concentrated to lines then is it possible to predict its self-evolution?

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Avoid Navier-Stokes evolution by:

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Biot-Savart Integral

Recovering the velocity field from the vorticity field.

A modicum of hope

Helmholtz-Hodge $\mathbf{v} = \mathbf{v}_c + \mathbf{v}_d + \nabla\phi,$

Road map and hurdles

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Helmholtz-Hodge $\mathbf{v} = \mathbf{v}_c + \mathbf{v}_d + \nabla\phi$, \mathbf{v}_c : Irrotational

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Biot-Savart Smooth, decaying, incompressible fields can be recovered via the Biot-Savart integral,

$$\mathbf{v}(\mathbf{x}) = \int_{\mathbb{R}^3} \frac{(\mathbf{x} - \boldsymbol{\omega}) \times d\boldsymbol{\omega}}{|\mathbf{x} - \boldsymbol{\omega}|^3} \quad (2)$$

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Problem: Integrals can be analytically hard and numerically

expensive. Solution: Constrain $\boldsymbol{\omega}$'s geometry.

Constraining the Vorticity

Better living through geometry

Vortex filament

$$\text{Let } \omega = \begin{cases} 1, & \mathbf{x} \in \xi \\ 0, & \mathbf{x} \notin \xi \end{cases},$$

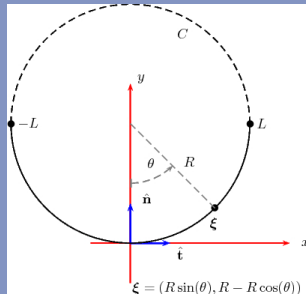
be such that

$$\xi = (R \sin(\theta), R - R \cos(\theta), 0)$$

where $R = \kappa^{-1} \in \mathbb{R}^+$ and

$$\theta \in D_L = (-L, L], \quad L \in [0, \pi].$$

Vortex filament in \mathbb{R}^2



Legend

Black (solid)=Vortex, Black (Dashed+Solid)=circle parameterization, Blue=Local Coordinates (Serret-Frenet), Gray=Spherical Field Point, Red=Global Coordinates

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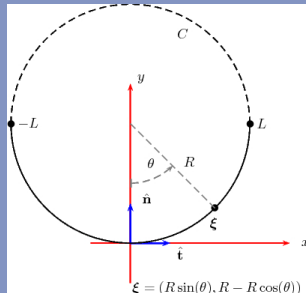
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What we hope to achieve

Prescription: $\xi = (R \sin(\theta), R - R \cos(\theta), 0)$

For the previous arc, the Biot-Savart integral becomes

$$\mathbf{v}(\mathbf{x}) = \int_{D_L} \frac{(\mathbf{x} - \xi) \times d\xi}{|\mathbf{x} - \xi|^3} \quad (3)$$

with elements

$$v_i(\mathbf{x}) = \int_{D_L} \frac{\epsilon_{ijk} (|\mathbf{x}|x_j - \xi_j) d\xi_k}{[|\mathbf{x}|^2 + |\xi|^2 - 2|\mathbf{x}|(x_1\xi_1 + x_2\xi_2 + x_3\xi_3)]^{3/2}} \quad (4)$$

Goal

Study (3) for $\varepsilon = |\mathbf{x}|/R = |\mathbf{x}|\kappa \ll 1$ and hopefully find an asymptotic representation as $\varepsilon \rightarrow 0$.

Local Induction Approximation

Local in space and 'periodic in time'

Local Induction

A curved vortex line induces the local flow.

$$\mathbf{V}(\mathbf{x}) \approx \frac{\kappa}{4\pi} \ln \left(\frac{L}{|\mathbf{x}|} \right) \hat{\mathbf{b}}$$

Derivation Method

- ♣: Differential Equations/Geometry
- ♣: Matched Asymptotics
- ♣: Vortex Curve

Chronology

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- 1965 R. Betchov
- 1967 G. K. Batchelor
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Local in space and 'periodic in time'

Local Induction

A curved vortex line induces the local flow.

$$\mathbf{V}(\mathbf{x}) \approx \frac{\kappa}{4\pi} \ln \left(\frac{L}{|\mathbf{x}|} \right) \hat{\mathbf{b}}$$

Derivation Method

- ♣: Differential Equations/Geometry
- ♣: Matched Asymptotics
- ♣: Vortex Curve

Chronology

- 1906 Levi-Civita & Da Rios
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Generalized Induction/Filament Equation

To Appear in the Journal of Mathematical Physics: arXiv:1102.2258

Theorem 1: GIE, directional component

$$\mathbf{V}_1(\varepsilon) = \varepsilon\beta_1\hat{\mathbf{t}} - \varepsilon\beta_2\hat{\mathbf{n}} + (\varepsilon\beta_2 + \varepsilon\beta_3 + \beta_4)\hat{\mathbf{b}}$$

The terms above imply movement in tangential direction ,
circulation about vortex core and binormal flow .

Theorem 2: Generalized Local Induction Equation

$$\mathbf{v}_\varepsilon(\mathbf{x}) = \kappa \left[\frac{72x_2^2 F_1(\lambda, k)}{2} - \frac{8x_2^2 E(L, k)}{(1-k^2)k} \right] \hat{\mathbf{b}}$$

The above formula implies that if ξ is the vortex arc then we
have the standard curvature driven binormal flow $\partial_t \xi \propto \kappa \hat{\mathbf{b}}$.

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Serret-Frenet Frame

A moving coordinate system for particle trajectories

Space Curve: $\xi : \mathbb{R} \rightarrow \mathbb{R}^3$

- Tangent: $\mathbf{T} = \xi'(s)$
- Normal: $\mathbf{N} = \frac{\mathbf{T}'}{\|\mathbf{T}'\|}$
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- Curvature: $\kappa = \|\mathbf{T}'\|$
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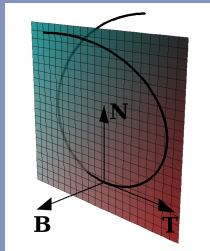
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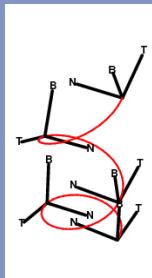
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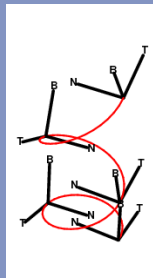
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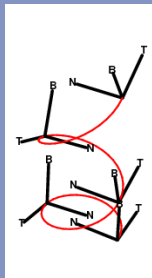
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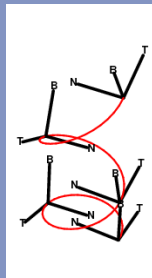
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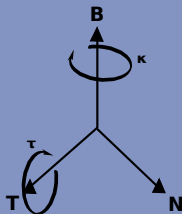
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Serret-Frenet Equations

Recovering trajectories through kinematic quantities

Recall: $\mathbf{T}' = \kappa \mathbf{N}$, $\mathbf{B}' = -\tau \mathbf{N}$

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Serret-Frenet ODEs

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Key Point

Up to rotations, translations and calculus, κ, τ can be used to recover the regular curve ξ .

Notes

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- SF are 9×9 system of ODEs
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$$\begin{bmatrix} \mathbf{T}' \\ \mathbf{N}' \\ \mathbf{B}' \end{bmatrix} = \begin{bmatrix} 0 & \kappa & 0 \\ -\kappa & 0 & \tau \\ 0 & -\tau & 0 \end{bmatrix} \begin{bmatrix} \mathbf{T} \\ \mathbf{N} \\ \mathbf{B} \end{bmatrix}$$

Key Point

Up to rotations, translations and calculus, κ, τ can be used to recover the regular curve ξ .

Notes

- SF are 9×9 system of ODEs
- SF are not generally autonomous
- The spectral problem is difficult

Serret-Frenet Equations

Recovering trajectories through kinematic quantities

Recall: $\mathbf{T}' = \kappa \mathbf{N}$, $\mathbf{B}' = -\tau \mathbf{N}$

- $|\mathbf{N}| = 1 \implies \langle \mathbf{N}', \mathbf{N} \rangle = 0$
- $\mathbf{N}' = \langle \mathbf{N}', \mathbf{T} \rangle \mathbf{T} + \langle \mathbf{N}', \mathbf{B} \rangle \mathbf{B}$
- $0 = \langle \mathbf{N}, \mathbf{T}' \rangle = \langle \mathbf{N}', \mathbf{T} \rangle + \kappa$
- $0 = \langle \mathbf{N}, \mathbf{B}' \rangle = \langle \mathbf{N}', \mathbf{B} \rangle - \tau$

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Hasimoto's Original Result

A clever transformation of binormal flow

Ingredients

- $\xi_t = \kappa \mathbf{B}$
- Conservation of Arclength
- Serret-Frenet Frame
- $\psi = \kappa e^{i\Phi}$, $\Phi = \int^s \tau ds'$
- $\mathbf{M} = (\mathbf{N} + i\mathbf{B})e^{i\Phi}$

Procedure

1. Compute binormal flow
2. $\xi = \kappa(\mathbf{N} + i\mathbf{B})e^{i\Phi}$
3. Compute Serret-Frenet frame
4. Compute $\psi = \kappa e^{i\Phi}$
5. Compute $\mathbf{M} = (\mathbf{N} + i\mathbf{B})e^{i\Phi}$

Results

- $\xi_t = \kappa \mathbf{B}$
- $\xi = \kappa(\mathbf{N} + i\mathbf{B})e^{i\Phi}$
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Procedure

- 1 ξ_{st} : from binormal flow
- 2 ξ_{ts} : from $(\mathbf{T}, \mathbf{M}, \bar{\mathbf{M}})$
- 3 $\xi_{st} = \xi_{ts}$: from arclength conservation
- 4 Equate terms

Results

- The wave-function obeys $i\psi_t + \psi_{ss} + 2^{-1}|\psi|^2\psi = 0$
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- \diamond Key Point: NLS $\rightarrow \kappa, \tau \rightarrow$ SF $\rightarrow \mathbf{T} \rightarrow \xi$

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The $SU(2)$ to $SO(3)$ map

Assuming a Darboux frame

Basis for $SU(2)$

$$U_1 = -i\sigma_z = \begin{bmatrix} -i & 0 \\ 0 & i \end{bmatrix}$$

$$U_2 = i\sigma_y = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$

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The isometry $SO(3) \rightarrow SU(2)$

- $U_1 = -i\sigma_z$
 - $U_2 = i\sigma_y$
 - $U_3 = i\sigma_x$
- A B \dots AB

Image of (e_1, e_2, e_3) under $SU(2)$

There exists an $\Omega \in SU(2)$ such that $E_i = \Omega^{-1}U_i\Omega$ where (E_1, E_2, E_3) is the image of the natural frame (e_1, e_2, e_3) .

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- Mapping 1:
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- Mapping 2:
 $\mathbf{x} \in \mathbb{R}^3 \rightarrow \sum_{i=1}^3 x_i U_i$
- Scalar Product:
 $\mathbf{A} \cdot \mathbf{B} = -2^{-1} \text{tr}(\mathbf{A}\mathbf{B})$

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Natural Serret-Frenet in the $SU(2)$

Fruits of the labor

Darboux Equations: $E_i = \Omega^{-1} U_i \Omega$

$$[U_1, \omega] = \kappa \cos(\Phi) U_2 + \kappa \sin(\Phi) U_3$$

$$[U_2, \omega] = -\kappa \cos(\Phi) U_1$$

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Results: $\Omega' = \omega \Omega$

Key Point: A procedure for curve reconstruction

We now have the inversion of the Hasimoto transformation:

$$VFE \rightarrow NLS \rightarrow \kappa, \tau \rightarrow q \rightarrow \omega \rightarrow \Omega \rightarrow E_1 \rightarrow \mathbf{e}_1 \rightarrow \xi$$

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Fruits of the labor

Darboux Equations: $E_i = \Omega^{-1} U_i \Omega$

$$[U_1, \omega] = \kappa \cos(\Phi) U_2 + \kappa \sin(\Phi) U_3$$

$$[U_2, \omega] = -\kappa \cos(\Phi) U_1$$

$$[U_3, \omega] = -\kappa \sin(\Phi) U_1$$

Results: $\Omega' = \omega \Omega$

$$\blacksquare \omega = -\kappa \cos(\Phi) U_3 + \kappa \sin(\Phi) U_2$$

$$\blacksquare \omega = \frac{i}{2} \begin{bmatrix} 0 & q \\ \bar{q} & 0 \end{bmatrix}$$

$$\blacksquare q(s) = \kappa e^{i\Phi}$$

Key Point: A procedure for curve reconstruction

We now have the inversion of the Hasimoto transformation:

$$\text{VFE} \rightarrow \text{NLS} \rightarrow \kappa, \tau \rightarrow q \rightarrow \omega \rightarrow \Omega \rightarrow E_1 \rightarrow \mathbf{e}_1 \rightarrow \xi$$

Conclusions

Thank you for your attention

Key Points

- 1 A vortex filament with nontrivial curvature will always display a binormal flow
- 2 Binormal Flow maps onto NLS
- 3 Using NLS one can theoretically recover the vortex geometry
- 4 Serret-Frenet obstructs analytic results but can be circumnavigated by using the $SU(2)$ formalism

Future Work

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- What PDE are possible for the case of vortex tubes?

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