

1 Metric Spaces

Definition A metric d on a space M satisfies the following:

- $d(x, y) = 0$ iff $x = y$
- $d(x, y) = d(y, x), \forall x, y \in M$
- $d(x, z) \leq d(x, y) + d(y, z)$

with $d : M \times M \mapsto [0, \infty)$.

Example: $l^p(\mathbb{R}, \mathbb{N})$ with $\|x\|_p = (\sum_{\mathbb{N}} |x_i|^p)^{1/p}$. In particular $l^1 \subset l^2 \dots l^\infty$. Also for $1 \geq p < q \geq \infty$, $l^q \subset l^p$.

Convergence in metric space: If $x_n \rightarrow x$ in (M, d) then $\forall \epsilon > 0, \exists N_\epsilon$ such that

$$n > N_\epsilon \Rightarrow d(x_n, x) < \epsilon$$

Cauchy convergence A sequence x_n is cauchy iff the following holds: $\forall \epsilon > 0$ there exists N_ϵ such that

$$n, m \geq N \Rightarrow d(x_n, x_m) < \epsilon$$

In particular if all Cauchy sequences converge in the space M then the space is complete. Also all converging sequences are Cauchy.

Coarseness If $x_n \rightarrow x$ in (M, d) implies that $x_n \rightarrow x$ in (M, d') then d is coarser than d' .

Equivalence of metrics: If two metrics are equivalent then

$$x_n \rightarrow x \text{ in } (M, d) \Leftrightarrow x_n \rightarrow x \text{ in } (M, d')$$

E.g. On \mathbb{R}^n all l^p norms are equivalent. An alternate characterization is the following: if given x and $\epsilon > 0, \exists \delta > 0$ such that

$$d'(x, y) < \delta \Rightarrow d(x, y) < \epsilon$$

and $\exists \delta' > 0$

$$d(x, y) < \delta' \Rightarrow d'(x, y) < \epsilon.$$

Continuity in Metric space Continuity of $f : V \mapsto W$ at v_0 can be defined through the following: $\forall \epsilon > 0$ there exists $\delta > 0$ such that

$$\|v - v_0\| < \delta \Rightarrow \|f(v) - f(v_0)\| < \epsilon$$

this is implied by $\|f(v)\|_W \leq C\|v\|_V$. Also can be defined sequentially, i.e. if $x_n \rightarrow x$ and if $f(x_n) \rightarrow f(x)$ then f is continuous.

Holder's inequality: For all sequences we have the following:

$$\sum_{\mathbb{N}} |x_i x_j| \leq \|x\|_p \|y\|_q$$

if $x \in l^p$ and $y \in l^q$, and further $1/p + 1/q = 1$.

Young's Inequality

$$ab \leq a^p/p + b^1/q$$

or more generally:

$$ab \leq \int_0^a f(t)dt + \int_0^b f^{-1}(t)dt$$

These are used to prove for example the Minkowski inequality for L^1, L^2 or the sequence space metrics etc.. See homework # 2.

2 Normed linear spaces = vector spaces

Definition We define a vector space V on a field F (usually on \mathbb{R}) with the following: First the properties of the vector space

1. $v + w = w + v$
2. $u + (u + w) = (u + v) + w$
3. $\exists 0 \in V, \text{ s.t. } 0 + u = u$
4. $\exists -v \in V, \text{ s.t. } -v + v = 0$

and operations involving the field elements $a, b \in F$:

1. $a(v + w) = av + aw$
2. $(a + b)v = av + bv$
3. $a(bv) = b(av)$
4. $1 \cdot v = v$ for 1 being the identity

The norm on this space satisfies the following conditions:

- $\|v\| \geq 0$
- $\|av\| = |a| \|v\|$

- $\|v + u\| \leq \|v\| + \|u\|$

A metric is thus defined for $d(x, y) = \|x - y\|$, so every vector space is a metric space.

Continuity of linear maps A linear map $f : (V, \|\cdot\|_V) \mapsto (W, \|\cdot\|_W)$ is defined with the following:

- $f(av + bw) = af(v) + bf(w)$
- $f(0_v) = 0_w$

The following are equivalent for normed spaces W, V :

- f is continuous
- f is continuous at 0.
- $\exists C < \infty$ such that $\|f(v)\|_W \leq C\|v\|_V$

The space of bounded linear maps is denoted $\mathcal{L}(V, W)$ and the following is true:

- if $W, \|\cdot\|_W$ is complete $\mathcal{L}(V, W)$ is complete
- We define the induced norm in this space as

$$\|f\|_{\mathcal{L}(V, W)} = \sup_{v \in V} \frac{\|f(v)\|_W}{\|v\|_V}$$

- $\|AB\|_{\mathcal{L}(V, W)} \leq \|A\|_{\mathcal{L}(V, W)}\|B\|_{\mathcal{L}(V, W)}$

E.g. For matrices we can find through the above that $\|A\|_1$ is the max row sum, $\|A\|_2 = \sqrt{\lambda_{max}}$, where λ_{max} is the max eigenvalue of $A^T A$, and finally $\|A\|_\infty$ is the max col sum.

Dual space V^* This is the space is in one-to-one correspondence to the space of bounded linear maps $\mathcal{L}(V, \mathbb{R})$. I.e. $f \in \mathcal{L}(V, \mathbb{R}) \Leftrightarrow v \in V^*$.

Banach spaces are vector spaces that are complete, i.e. all Cauchy sequences converge in the space itself. **E.g.** $C[a, b]$ with $\|\cdot\|_\infty$ is complete as well as C_0 with $\|\cdot\|_\infty$. Counterexamples include $C[a, b]$ with L^2 norm or l_c (sequences with finite non-zero terms) with any l^p norm.

Semi-norms A semi-norm $p = L(v)$ for $v \in V$ and $L \in \mathcal{L}(V, \mathbb{R})$ satisfies

- $p(av) = |a|p(v)$
- $p(v + w) \leq p(v) + p(w)$

E.g. In particular we can build the l^1 norms on \mathbb{R}^2 through appropriate choices of p_1 and p_2 and take the supremum over seminorms. I.e. define $p_1 = x + y$ and $p_2 = x - y$ to produce that

$$\|(x, y)\|_1 = \sup_{i=1,2} p_i(v)$$

For the l^2 norm we need an arbitrary collection $p_a = x \cos a + y \sin a$. Its supremum over all $a \in [0, 2\pi]$ gives the 2-norm on vectors. In general we can build norms out of seminorms when $\forall v \neq 0 \Rightarrow p(v) > 0$. The mechanism we use is summing over many norms or taking a supremum.

3 Hilbert Spaces

Definition. Normed linear spaces that are complete. Norm must satisfy parallelogram law:

$$\|x + y\|^2 + \|x - y\|^2 \leq 2\|x\|^2 + 2\|y\|^2$$

Cauchy-Schwartz says

$$|\langle x, y \rangle| \leq \|x\|_H \|y\|_H$$

For M a closed linear space we can show that

$$M \oplus M^\perp = H$$

so we can decompose any $z \in H$ as $z = u + v$ for $u \in M$ and $v \in M^\perp$.

Also (for convex subspace as well), we can find unique $w \in M$ such that

$$\min_{v \in M} \|z - v\| = \|w - z\|, \quad w \in M$$

4 Topological Spaces

Definition The following 3 axioms define a topology \mathcal{T} on a set X which is a collection of open sets,

- $\emptyset, X \in \mathcal{T}$
- Finite intersections are in space itself i.e. $U, V \in \mathcal{T} \Rightarrow U \cap V \in \mathcal{T}$.
- Arbitrary unions are in space as well i.e. $U_\alpha \in \mathcal{T}$ then $\bigcup_{\alpha \in A} U_\alpha \in \mathcal{T}$.

An open U is defined such that $\forall y \in U, \exists V$ such that $y \in V \subseteq U$.

The **relative topology** is the topology that is restricted to a subset $YG \subseteq X$ such that

$$S = \{H \subset Y \mid H = G \cap Y, G \in \mathcal{T}\}$$

A **Hausdorff** topology is such that for all $x, y \in X$ there exists open sets $U \ni x, V \ni y$ such that $U \cap V = \emptyset$.

A subset $V \subset X$ is a **neighborhood** of $x \in X$ if V is open and $V \ni x$.

Convergence in topological sense is defined through the following: $x_n \rightarrow x$ iff $\forall V \in \mathcal{N}(x)$ there exists N such that

$$n \geq N \Rightarrow x_n \in V$$

Continuity at a point is given by the following: for $f : X \mapsto Y$ then for f to be continuous at $x \in X$ then $\forall W \in \mathcal{N}(f(x)), \exists V \in \mathcal{N}(x)$ such that $f(V) \subseteq W$.

Continuity of functions in the topological sense is implied by the following: Let $(X, \mathcal{T}$ and (Y, \mathcal{S}) are topological spaces, then $f : X \mapsto Y$ is continuous iff $f^{-1}(G) \in \mathcal{T}$ for all $G \in \mathcal{S}$. Note that sequential continuity does not directly imply the above (example is co-countable topology on \mathbb{R}).

A **Homeomorphism** is a function that is one-to-one and onto.

A **Neighborhood or local base** is defined through the following axioms:

- $V \in \mathcal{N}(x) \Rightarrow x \in V$
- If $U, V \in \mathcal{N}(x)$ then $\exists W \in \mathcal{N}(x)$ such that $W \subset V \cap U$.
- If $V \in \mathcal{N}(x)$ there exists $W \in \mathcal{N}(x)$ such that $W \subset V$
 - $W \subset V$
 - $y \in W \Rightarrow \exists U \in \mathcal{N}(y)$ and $U \subset V$.

We can define a topology using the local base i.e. O is open is $\forall x \in O$ there exists $V \in \mathcal{N}(x)$ such that $V \subseteq O$.

A **base** is defined through the following axioms for $B \in \mathcal{B}$:

- $\bigcup_{B \in \mathcal{B}} B = X$
- For $B_1, B_2 \in \mathcal{B}$ and $x \in B_1 \cap B_2$ then there exists $(B_3 \ni x) \in \mathcal{B}$ such that $B_3 \subseteq B_1 \cap B_2$.

Additionally we can defined the unique topology \mathcal{T} on X defined through the base above through

$$O \in \mathcal{T} \Rightarrow \forall y \in O, \exists B \in \mathcal{B} \text{ such that } (B \ni y) \subseteq O$$

In particular we can thus find that in $O \in \mathcal{T}$ then therefore $O = \bigcup_{U \in \mathcal{B}, U \subseteq O} U$.

The **weak topology** on X is defined as the topology that makes all linear functionals continuous, i.e. $f \in \mathcal{L}(V, \mathbb{R})$ is continuous.

Finally a countable local base makes the space **first countable**. A countable base or basis gives a **second countable**. In addition we prove that the space is second countable iff it is **separable** which implies that there is a countable set $\{x_n\} \subset M$ such that given any $x \in M$ and $\epsilon > 0$ then $\exists x_n$ such that $d(x_n, x) < \epsilon$.

5 Size of sets

5.1 Small/largeness

Dense set A set A is dense in X if $U \cap A \neq \emptyset$ for all $U^{open} \subset X$.

Interior points $A \subset X$, a point $x \in A$ is an interior point if $\exists U^{open} \ni x$ such that $U \subset A$. Therefore

$$A^\circ = \{x \mid x \in \text{interior of } A\} = \bigcap_{V^{open} \subset A} V$$

Closure For $A \subset X$, $x \in \bar{A}$ if for all $V^{open} \ni x$, $V \cap A \neq \emptyset$ or

$$\bar{A} = \{x \mid x \in \text{closure of } A\} = \bigcap_{A \subseteq F, F \text{ closed}} F$$

It is a fact that $A^\circ \subset A \subset \bar{A}$, and so we can give the interpretation that A° is open, \bar{A} is closed.

Nowhere dense $A \subset X$ is nowhere dense if \bar{A} has empty interior, i.e. $(\bar{A})^\circ = \emptyset$. Also, A is nowhere dense if $(A^c)^\circ = X$ or its complement's interior is dense.

Meager or 1st category sets if A is the countable union of nowhere dense sets, then A is meager or 1st category. For example $\{r_n\}$ is an enumeration of the rationals and so since \mathbb{Q} is a countable union of single element sets, then it is meager. A single element set is nowhere dense.

2nd category or residual sets Simply, the complement of a meager set is residual.

Density (again) If $A \subset X$ is dense in X then $\bar{A} = X$. Also, if $A \subset X$ is dense in B , then $B \subset \bar{A}$. Also, A is dense in X if and only if its complement has empty interior, i.e. $(A^c)^\circ = \emptyset$.

very small	nowhere dense
very large	dense interior
small	meager
large	residual
medium small	empty interior
medium large	dense

Measure zero A subset A of \mathbb{R}^n has measure zero (or Lebesgue measure zero) if $\forall \epsilon > 0$, there is a countable collection $\{B_n\}$ of open balls $B_n = B(x_n, \delta_n) = \{x \mid \|x - x_n\|_2 < \delta_n\}$ such that

$$A = \bigcup_{n=1}^{\infty} B_n$$

and $\sum_{n=1}^{\infty} \text{volume of } B_n \leq \epsilon$. Example: \mathbb{Q} in \mathbb{R} . The Cantor middle thirds set has measure zero even though this set has measure zero. Any countable union of elements have measure zero.

Generic sets Let (X, \mathcal{T}) be a topological space. A property P is generic (in the sense of Baire category) if

$\{x \mid P(x) \text{ is true}\}$ is a dense residual set

E.g. The property of being an irrational number is generic since the complement is meager (\mathbb{Q}) and \mathbb{Q}^c is dense. The set of differentiable fcn's in $C[0, 1]$ is not generic. The property of quadratic equations to have distinct roots is generic.

Zariski generic sets Let $X = \mathbb{R}^n$, and equip it with the Zariski topology. A set in this topology is considered open if its complement is the solution to a system of polynomial equations. The closed sets have measure zero. Therefore a property is generic if the set of x that have property P is a Zariski generic set. Equivalently, the set not having the property is given by the solution set of finitely many algebraic equations.

E.g. A quadratic equation $x^2 + bx + c$ has non-distinct roots when $b^2 - 4c = 0$, therefore it is Zariski closed, and thus the property of *not* having this property is Zariski generic.

Baire category theorem?

5.2 Measure theory

A **Measurable space** is a set X together with a collection of subsets \mathcal{B} of X satisfying:

$$X \in \mathcal{B}, \emptyset \in \mathcal{B}$$

$$\text{if } A \in \mathcal{B} \Rightarrow A^c \in \mathcal{B}$$

$$\text{if } A_1, A_2, \dots \in \mathcal{B} \Rightarrow \bigcup_{n=1}^{\infty} A_n \in \mathcal{B}$$

\mathcal{B} is called a σ -algebra. Also closed under countable intersections.

A **Measure** μ satisfies the following relations on a measurable space (X, \mathcal{B}) ,

$$\mu : \mathcal{B} \mapsto [0, \infty]$$

$$\text{such that } \mu(\emptyset) = 0$$

$$\text{and } \mu\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} \mu(A_n)$$

whenever the set $\{A_n\}$ are mutually disjoint and belong to \mathcal{B} .

E.g. we can prove the following: Let $A \subset B$ then $B = (B - A) \cup A$ and $\mu(B) = \mu(B - A) + \mu(A)$. Also if $\mu(A) \leq \mu(B)$. More importantly, if $A_n \in \mathcal{B}$ and $A_1 \supset A_2 \dots$ then

$$\mu\left(\bigcap_{n=1}^{\infty} A_n\right) = \lim_{n \rightarrow \infty} \mu(A_n)$$

also let $B_k \in \mathcal{B}$, then

$$\mu\left(\bigcup_{n=1}^{\infty} B_n\right) \leq \sum_{n=1}^{\infty} \mu(B_n)$$

The Borel σ -algebra is the smallest such σ -algebra containing all the open sets in a topology \mathcal{T} .

disjointness is important in proving the results concerning the measure. Therefore if given a general set $\{E_i\} \in \mathcal{B}$, then define

$$F_1 = E_1, F_2 = E_2 \cap F_1^c, \text{ or } F_j = E_j \cap \bigcap_{n=1}^{j-1} F_n^c$$

6 Convergence and compactness

6.1 Convergence and completeness

Convergence in topological space for a sequence $x_n \rightarrow x$ is given by for each open sets or neighborhoods of x , V , then $\exists N$ such that

$$n > N \Rightarrow x_n \in V$$

Convergence in metric space (X, d) assumes more structure, i.e. for all $\epsilon > 0$, $\exists N_\epsilon$ such that

$$n > N_\epsilon \Rightarrow d(x_n, x) < \epsilon$$

Cauchy convergence A sequence is Cauchy if $\forall \epsilon > 0$, $\exists N_\epsilon$ such that

$$m, n \geq N_\epsilon \Rightarrow d(x_n, x_m) < \epsilon$$

A metric space is called **complete**, if every Cauchy sequence converges in the cited metric space. E.g. the rationals are incomplete, consider $x = 1$, $x_n = x_{n-1} + 1/x_n$, this sequence converges to $\sqrt{2} \notin \mathbb{Q}$. In function spaces the sequence $t^n \in C[0, 1]$ is Cauchy in metric L^1 but it converges to a discontinuous function.

Conversely, \mathbb{R}^2 with euclidean norm is complete or even $l^p(\mathbb{R}, \mathbb{Q})$. Also, $C[0, 1]$ under the supremum or L^∞ norm.

Contraction mapping theorem For a complete metric space (M, d) , let $f : M \mapsto M$ be a continuous function and suppose that $\exists 0 < k < 1$ such that

$$d(f(x), f(z)) \leq kd(x, z), \forall x, z \in M$$

then there exists a unique $y \in M$ such that $f(y) = y$.

For example Newton's method requires the computation $x_{n+1} = x_n - g(x_n)/g'(x_n)$, so we can show that $f(x) = x - g(x)/g'(x)$ is a contraction mapping for $g \in C^2[0, 1]$ ($2 \times$ differentiable).

Baire category theorem In a complete metric space, every residual set is dense.

Further, this implies that every complete metric space is *not* a countable union of disjoint nowhere dense sets.

6.2 Completions

An **equivalence relation** on X is a subset of $X \times X$, i.e. a subset of pairs $\{(x_1, x_2) | x_1, x_2 \in X\}$ or written $x_1 \sim x_2$ that satisfy the conditions:

- (i) $x_1 \sim x_1$
- (ii) $x_1 \sim x_2 \Rightarrow x_2 \sim x_1$
- (iii) $x_1 \sim x_2, x_2 \sim x_3 \Rightarrow x_1 \sim x_3$

An **equivalence class** of x denoted $[x]$, is the set of points equivalent to it, i.e.

$$[x] = \{y | y \sim x\}$$

The **completion** of a possible incomplete metric space (M, d) is defined in the following way: if $\{y_n\}$ and $\{x_n\}$ are two Cauchy sequences in M we say define the equivalence relation between sequences as $\{x_n\} \sim \{y_n\}$ if $d(x_n, y_n) \rightarrow 0$ as $n \rightarrow \infty$. \overline{M} is the collection of all the equivalence classes of Cauchy sequences in M . For such a space define the distance metric as \overline{d} ,

$$\overline{d}([\{x_n\}], [\{z_n\}]) = \lim_{n \rightarrow \infty} d(x_n, z_n)$$

Misc. things we can prove: \overline{d} always exists, the specific Cauchy sequence does not affect the value of \overline{d} , \overline{d} is a metric, and $(\overline{M}, \overline{d})$ is a complete metric space. Defining the constant sequence x , then the \overline{d} metric collapses to the metric in d . Also, M is dense in \overline{M} .

6.3 Compactness

The property of **compactness** *morally* approximates the properties of finite sets, in fact all finite element sets are compact. More generally we define a compact set on metric spaces according to the following definition: For a compact set $A \subset X$, any sequence $\{x_n\} \in A$ has a *convergent subsequence* $\{x_{n(k)}\}$

E.g. trivially, $\{1, -1, 1, -1, \dots\}$ has a convergent subsequence to ± 1 . The real numbers are compact, consider $x_n = n$, it has no convergent subsequence.

Things we can prove: a compact metric space is complete. A compact subset A of a metric space must be closed and bounded. The converse is not true. \mathbb{R} is closed unto itself but clearly not compact. Also, you can be bounded but not compact, i.e. $(0, 1]$.

A **bounded** set A is defined by the parallel constructions that

$$\exists K > 0, \text{ such that } d(x, y) < K, \forall x, y \in A$$

$$\exists x_0 \in A, P < \infty \text{ such that } d(x_0, y) < P, \forall y \in A$$

Heine-Borel Theorem A subset A of \mathbb{R}^n is compact iff it is closed and bounded. A corollary states that every bounded sequence in \mathbb{R}^n has a convergent subsequence.

Now we will deal with properties of **continuous functions on compact sets**, i.e.

- For $f : M \mapsto \mathbb{R}$ continuous, and so $\exists x_{\pm}$ such that for all $x \in M$ then

$$a = f(x_-) \leq f(x) \leq f_+(x) = A$$

There is also a parallel definition of compactness for a topological space (X, \mathcal{T}) , i.e. consider $\{U_{\alpha}\}$ a possibly uncountable open covering of a set $A \subset X$, i.e.

$$A \subset \bigcup_{\alpha} U_{\alpha}$$

then if A is compact there exists a *finite* subcovering, i.e.

$$A \subset \bigcup_{n=1}^N U_{\alpha_n}$$

for all open coverings. The definition for a space itself is directly analogous.

A related property is the so-called **finite intersection** property, i.e. if $\{F_{\alpha}\}$ is a collection of closed subsets of a topological space (X, \mathcal{T}) then the collection has this property if a finite intersection of such sets is non-empty:

$$\bigcap_{i=1}^N F_{\alpha_i} \neq \emptyset$$

If a topological space is compact then for any collection of closed sets that has the finite intersection property, then

$$\bigcap_{\alpha} F_{\alpha} \neq \emptyset$$

Related facts: A closed subset of a compact topological space is compact. Also, a compact subset of a Hausdorff space is closed.

6.4 Uniformity

Definition of uniform continuity: Let $f : (M, d) \mapsto (M', d')$ (metric spaces) then f is uniformly continuous if $\forall \epsilon > 0, \exists \delta > 0$, such that

$$d(x, y) < \delta \Rightarrow d'(f(x), f(y)) < \epsilon$$

Note δ depends only on ϵ , and not x which refers to pointwise convergence.

Fact: A continuous function from a compact metric space inherits some structure from the domain, and thus f is uniformly continuous.

Now we define **pointwise convergence** of functions: Let (M, d) and (M', d') be metric spaces, then $\{f_n\}$ are a sequence of functions from M to M' and suppose that $f : M \mapsto M'$, then if

$$\lim_{n \rightarrow \infty} f_n(x) = f(x) \forall x \in M$$

then f_n approaches f **pointwise!**

Now for **uniform convergence**. Then if $\forall \epsilon > 0, \exists N$ such that

$$n > N \Rightarrow d'(f_n(x), f(x)) < \epsilon, x \in M$$

The **Weierstrass M-test**: Suppose f_n are a sequence of functions in (M, d) and suppose that

$$\|f_n\|_{\infty} \leq a_n, \text{ with } \|a_n\|_1 < \infty$$

then the partial sums converge uniformly for large enough m , i.e.

$$\sum_{n=1}^{\infty} f_n(x) \text{ converges uniformly}$$

The **uniform limit of continuous functions is continuous!** It means that $C(M)$ is complete for (M, d) a metric space.

Term-by-term differentiation Suppose $f(x) = \sum_{n=1}^{\infty} f_n(x)$ converges uniformly on some interval $J \subset \mathbb{R}$ and also the sum of the derivatives, $g(x) = \sum_{n=1}^{\infty} f'_n(x)$ converges uniformly as well, then $f'(x) = g(x)$.

This is related to the fact that the property of *not* having a derivative is generic.

Integration of a uniformly convergent sequence is allowed but can be relaxed (using Lebesgue integration). At present, knowing that $\{f_n\}$ is a uniformly convergent sequence on $[a, b]$ then

$$\lim_{n \rightarrow \infty} \int_a^b f_n(x) dx = \int_a^b f(x) dx$$

Now we turn to parametrized integrals. So we define uniform convergence for integrals, i.e.

$$\int_{\mathbb{R}} f(t, x) dx = F(t)$$

converges uniformly to $F(t)$ for $t \in [a, b] \subseteq \mathbb{R}$, if for every $\epsilon > 0$ there is an R_0 depending on ϵ but not t , such that for all $R > R_0, \forall t \in [a, b]$,

$$\left| \int_{-R}^R f(t, x) dx - F(t) \right| < \epsilon$$

Differentiating parametrized integrals, can be done under the hypothesis that

$$\int_{\mathbb{R}} f(t, x) dx = F(t), \int_{\mathbb{R}} \frac{\partial f}{\partial t} dx = G(t) \text{ converge uniformly}$$

then $F'(t) = G(t)$.

7 Lebesgue Integration

The motivation for developing the idea of Lebesgue integration comes from consideration of the completion of $C[0, 1]$ under the L_1 metric for example. It turns out these are measurable functions and the metric is Lebesgue integration (?).

Define $U(f, \Delta) = \sum_{i=0}^n \max_{x \in (t_i, t_{i+1})} f(t)(t_{i+1} - t_i)$ and $L(f, \Delta) = \sum_{i=0}^n \min_{x \in (t_i, t_{i+1})} f(t)(t_{i+1} - t_i)$. These are approximations to the integral/area under the curve of f . Therefore the limiting process of the can be defined:

$$U(f) = \inf_{\Delta} U(f, \Delta), L(f) = \sup_{\Delta} L(f, \Delta)$$

In particular if f is Riemann integrable then $U(f) = L(f)$ and so for any continuous function this condition is met since they will be Riemann integrable. Can also that a general function on $[0, 1]$ is Riemann integrable if and only if the set of points of discontinuity of f is of Lebesgue measure zero.

We define **measurable functions**, take (X, \mathcal{B}) and (Y, \mathcal{C}) be measurable spaces, then a function $f : X \mapsto Y$ is measurable if $f^{-1}(A) \in \mathcal{B}$ for all $A \in \mathcal{C}$.

This definition can be extended to the case that really interest us, which means that $Y = \mathbb{R}$. Therefore first define the extended real numbers:

$$\mathbb{R}_{ex} = \mathbb{R} \cup -\infty, \infty = [-\infty, \infty]$$

with the following rules : $a \in \text{real}, a \pm \infty = \pm\infty$, if $a > 0$, then $a \times \pm\infty = \pm\infty, 0 \times \pm\infty = 0, \infty - \infty$ is undefined.

So consider (X, \mathcal{B}) a measurable space. Then $f : X \mapsto \mathbb{R}_{ex}$ is measurable if the set

$$\{t \mid f(t) < \alpha\} \in \mathcal{B}, \alpha \in \mathbb{R}$$

This property is inherited to a sequence of such functions, i.e. if $\{f_n\}$ are measurable then if $f_n \rightarrow f$ pointwise, then f is measurable.

7.1 Lebesgue integral

From here on we expect (X, \mathcal{B}, μ) is the domain. Firstly lets define the characteristic function, i.e. $\chi_A(x)$ such that

$$\chi_A(x) = \begin{cases} 1, & x \in A \\ 0, & x \notin A \end{cases}$$

A nonnegative simple function Let $A_1 \dots A_n \subset X$ be pairwise disjoint measurable sets, a function

$$\phi(x) = \sum_{j=1}^n \alpha_j \chi_{A_j}$$

then ϕ is a simple function (step function). Within the Lebesgue theory we expect that

$$\int \phi = \sum_{j=1}^n \alpha_j \mu(A_j)$$

The idea is to approximate the integral of a general function f with successive simple functions of increasing n .

So let $f : X \mapsto [0, \infty]$ and measurable, then its Lebesgue integral is given by

$$\int f = \sup_{0 \leq \phi \leq f, \phi \text{ simple}} \int \phi$$

Now consider a general function that can take negative values, then we can integrate each part separately, i.e. $f = f_+ - f_-$. Work out which one is positive/negative! hah!

There is a analogy to sequence where the measure is the number of points in a set. The function is the sequence. See page 355.

For non-negative fcn's the Lebesgue integral retain linearity and positive definiteness, and the the integral is zero iff f is zero almost everywhere = the set where the function is not zero is measure zero.

7.2 Convergence theorems

Fatou's Lemma We introduce first the idea of **limit inferior** and **limit superior**. In the sense of real numbers

$\liminf a_n =$ least limit point of the sequence

or the least point such that for any open set containing it, there are only finite number of points to the left. Similarly for $\limsup a_n$,

$\limsup a_n =$ greatest limit point of the sequence

If the series converges, then these two things are equal. For **Fatou's lemma** we use the notion that things can't escape to ∞ , i.e.,

$$\int_X \liminf f_n d\mu \leq \liminf \int f_n d\mu$$

Monotone convergence theorem states that if we have a sequence of non-negative measurable functions $\{f_n\}$ such that $f_{n+1}(x) \geq f_n(x)$ for each x (a non-decreasing set) and $\lim f_n = f$ (pointwise) then

$$\lim \int f_n dx = \int \lim f_n dx$$

Note: power series can be integrated term by term in compact subsets of their interval of convergence.

Dominated convergence theorem states that for a sequence $\{f_n\}$ that can be dominated $|f_n| \leq g$ and $\lim f_n = f$ a.e. and g is integrable, then

$$\lim \int f_n dx = \int \lim f_n dx$$

7.3 Lebesgue spaces

Let (X, \mathcal{B}, μ) be a measure space. $L^p(X)$ ($1 \leq p < \infty$) is the linear space of equivalence classes of measurable, L^p -integrable functions from X to \mathbb{R}_{ex} . Two functions are measurable if they differ only on a set of measure zero. Therefore $0 \sim \{1, x \in \mathbb{Q}, 0, x \in \mathbb{Q}^c\}$.

The case of $p = \infty$ is different. We define that $L^\infty(X, d\mu)$ is the set of equivalence classes of measurable functions with the following property:

$$\exists M > 0, \text{ such that } |f(x)| \leq M, \text{ for a.e. } x \in X$$

The equivalence class is as before, $f \sim g$ if they differ only on a set of measure zero. The norm is actually called the essential supremum, i.e.

$$\text{ess sup } f = \inf M$$

Cauchy sequence in L^∞ : Let $\{f_n\}$ be a Cauchy sequence in $L^\infty(X)$, then there is a set $E \subset X$ of measure zero with the property that $\forall \epsilon > 0, \exists N$ such that

$$|f_n(x) - f_m(x)| < \epsilon, \forall x \in X - E \text{ whenever } n, m > N$$

Another important aspect is the **Riesz-Fischer Theorem**, for $1 \leq p \leq \infty$, $L^p(\infty)$ is a complete metric space. Also, $L^p(\infty)$ are normed linear spaces.

Chebyshev's Inequality Let f be a measurable, extended real-valued function on a measure space (X, \mathcal{B}, μ) . For every $\epsilon > 0$,

$$\mu(\{x \mid |f(x)| > \epsilon\}) \leq \frac{1}{\epsilon} \int |f| d\mu$$

Regular Let (X, \mathcal{T}) be a topological space and suppose that X is locally compact: every $x \in X$ has a neighborhood whose closure is compact. Let μ be a measure defined on \mathcal{B} (Borel σ -algebra). Then μ is **regular** if for every measurable set E ,

$$\begin{aligned} \mu(E) &= \inf\{\mu(O) \mid O \supseteq E, O \text{ open}\} \\ &= \sup\{\mu(K) \mid K \subseteq E, K \text{ compact}\} \end{aligned}$$

It means that the measure of a set E can be approximated by a compact set enclosing it, or open sets contained in E . An alternate definition (or consequence of the above): A measure is Borel regular if $\forall E$ measurable and $\epsilon > 0$,

$$\exists O^{open}, O \subseteq E, K^{compact} \supseteq B \text{ such that } \mu(O - E) < \epsilon, \mu(B - K) < \epsilon$$

The crowning achievement: **denseness** of C_0^∞ , if μ is Borel regular measure on X then continuous functions with compact support are dense in $L^p(X)$ for $1 \leq p < \infty$. Shankar's advice:

- Convergence in L^p (or more generally, convergence of integrals) does not imply pointwise convergence. However, one can usually extract subsequences that converge pointwise.

E.g. The halves example. They converge in L^p but do not converge pointwise. However, we can extract a subsequence that converges. Since it's a Cauchy sequence, the sequence converges to this.

- Chebyshev's inequality. See above.
- L^1 (or more generally L^p) is a complete normed linear space. For $p < \infty$, it is the completion of the $C_0^\infty(\mathbb{R})$ with respect to the L^p metric. In particular, this implies that the compactly supported continuous (and also smooth) functions are dense in L^p .

References

Principles of Analysis, H. Flaschka, University of Arizona