

1. The arm of the pendulum oscillates as  $l = l_0 + a \cos(\Omega t)$ . Find Lagrangian  $L = \frac{1}{2}mv^2 - U(x, y)$  and derive the equation of motion in terms of angle  $\varphi(t)$  (see your notes), here  $x(t) = l(t) \sin \varphi(t)$ ,  $y(t) = l(t) \cos \varphi(t)$ ,  $v^2 = (x'(t))^2 + (y'(t))^2$  and the potential energy has following form:  $U = -mgl(t) \cos \varphi(t)$

2. Solve the equation  $x''(t) + \omega_0^2 x(t) = B \sin \Omega t$ , ( $\omega_0 \neq \Omega$ ) with following initial conditions:  $x(0) = 0$ ,  $x'(0) = 0$

3. Solve the equation  $x''(t) + \omega_0^2 x(t) = B \sin \omega_0 t$ , with following initial conditions:  $x(0) = 0$ ,  $x'(0) = 0$ . Hint - use substitution  $x(t) = At \sin(\omega_0 t + \varphi) + x_0(t)$ , here  $x_0(t)$  is the general solution of homogeneous equation (equation without right hand side term).

4. Find inhomogeneous solution of the equation:  $x''(t) + \gamma x'(t) + 4x(t) = \sin \Omega t$ , here  $\gamma > 0$ . Using Matlab plot dependence of the amplitude and phase  $\varphi$  of this solution on  $\Omega$  ( $1 \leq \Omega \leq 6$ ) for  $\gamma = 0.1, 0.2, 0.4, 0.6, 0.8, 1.0$