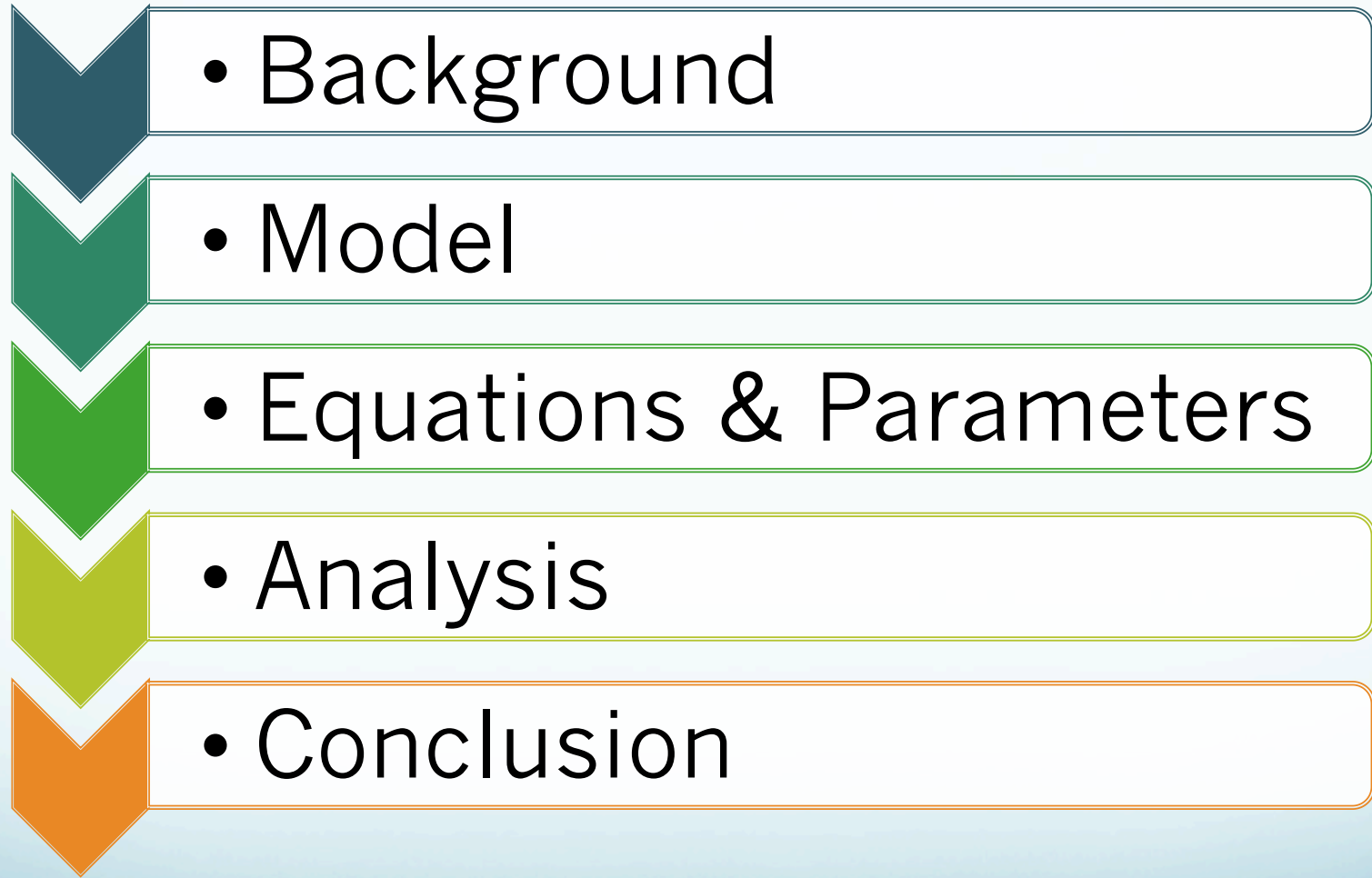


Shock-Induced Termination of Cardiac Arrhythmias

**Baltazar Chavez-Diaz; Sarah Schwenck; Weide Wang;
Jinglei Zhang; Chen Jiang
Mentor: Katie Williams**

Presentation Overview



Background

Model

Equations &
Parameters

Analysis

Conclusion

Cardiac Arrhythmias

Cardiac dysrhythmia or irregular heartbeat

Irregular **Electrical** activity of the heart

Regular or irregular

Background

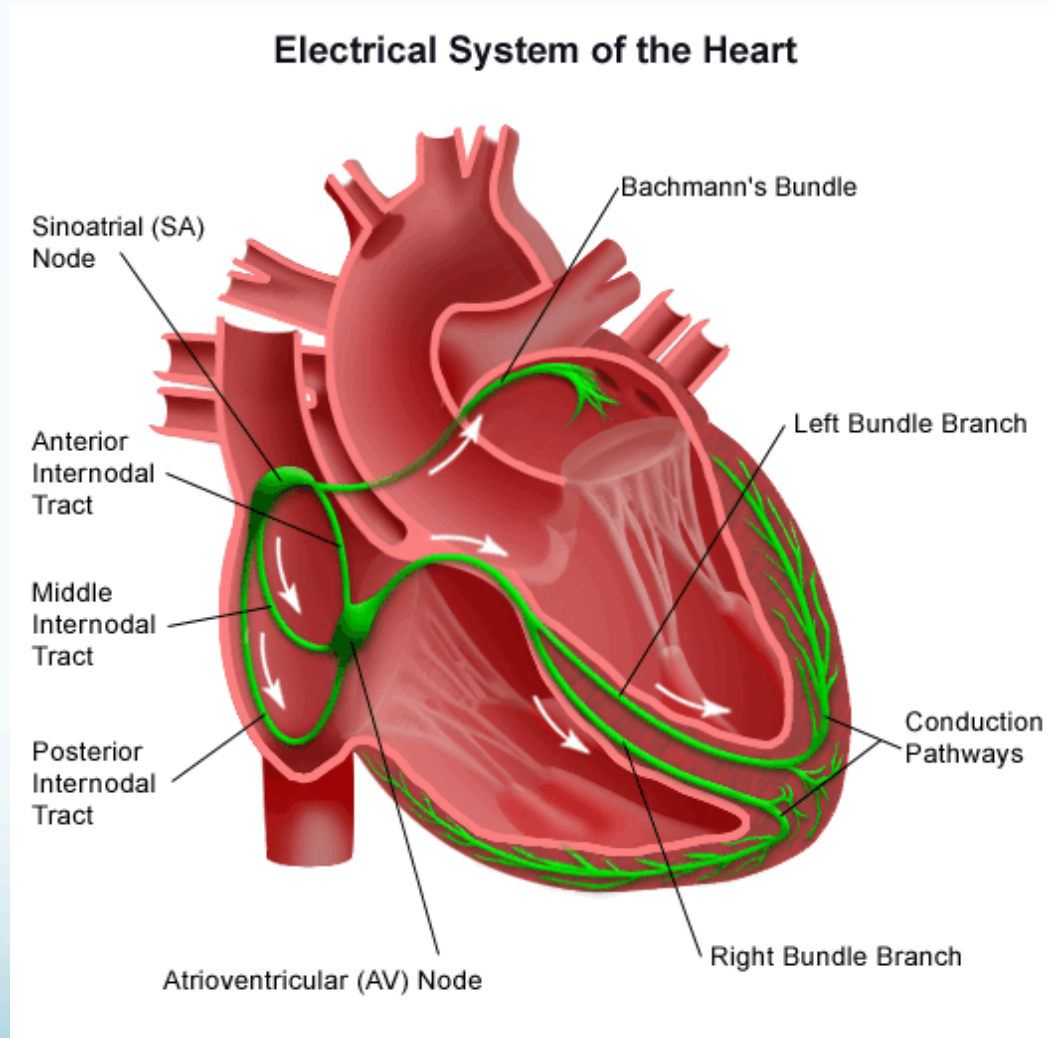
Model

Equations &
Parameters

Analysis

Conclusion

Cardiac Arrhythmias



Background

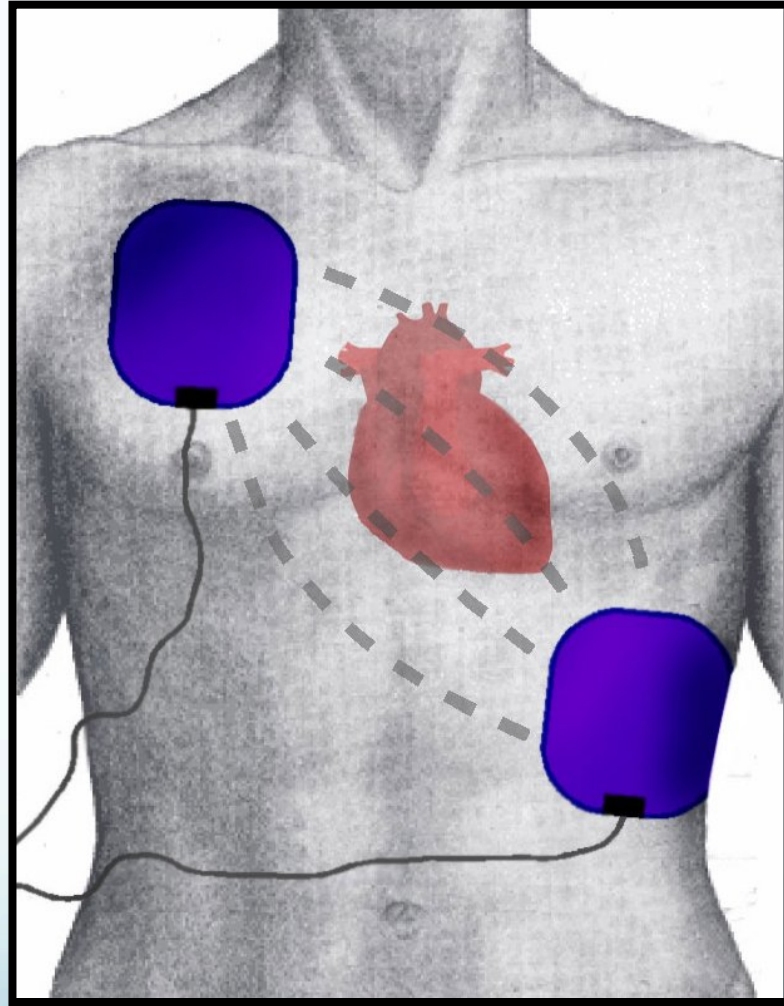
Model

Equations &
Parameters

Analysis

Conclusion

Defibrillators



Background

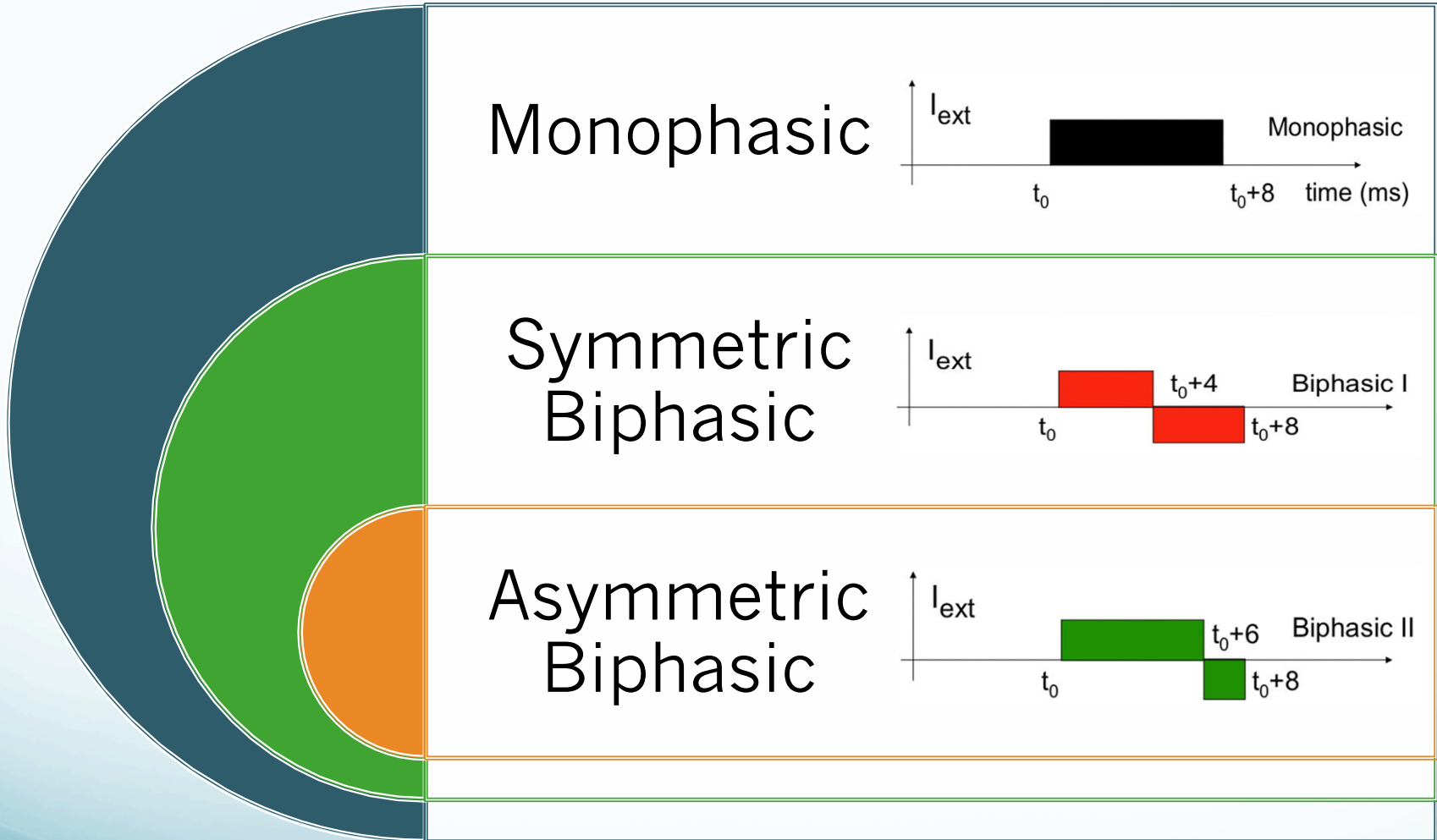
Model

Equations &
Parameters

Analysis

Conclusion

Defibrillators



Background

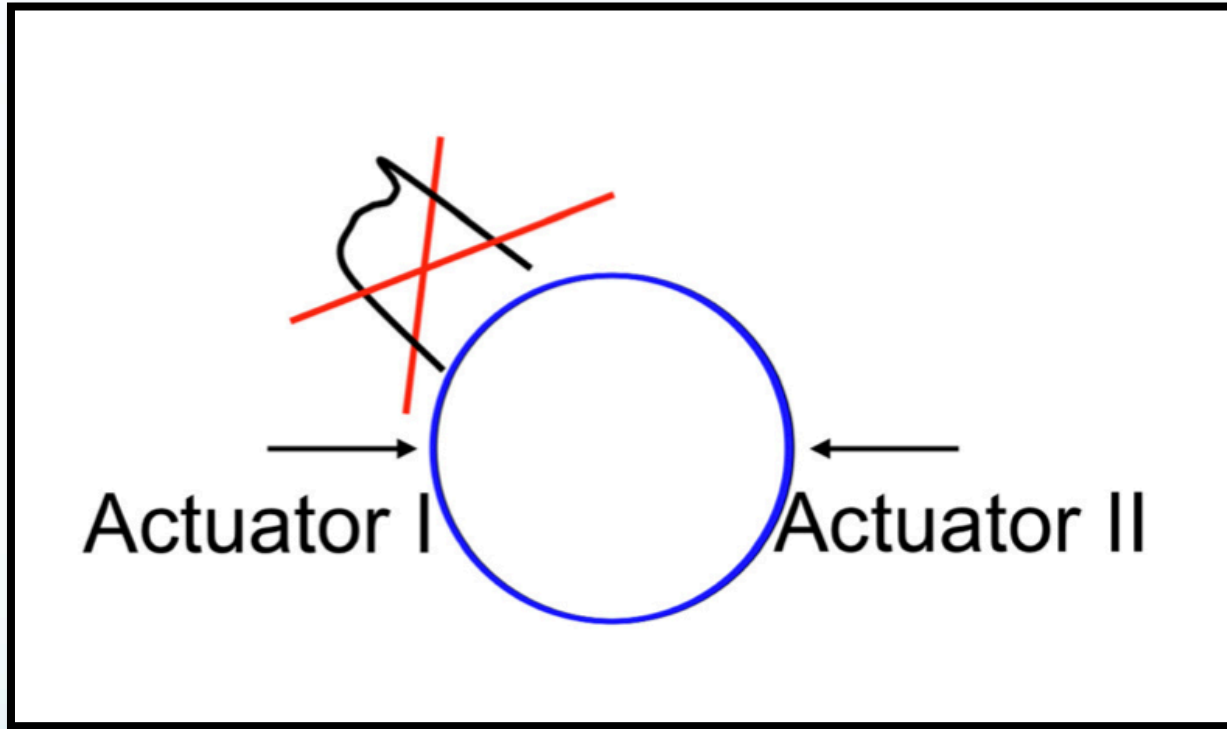
Model

Equations &
Parameters

Analysis

Conclusion

Model



Background

Model

Equations &
Parameters

Analysis

Conclusion

Parameter influencing the defibrillation outcome

- 1) The shock waveform
- 2) The shock duration
- 3) The shock energy
- 4) Shock timing
- 5) Dynamical state at the time of the shock
- 6) Heterogeneity of the cardiac tissue
- 7) System size

Background

Model

Equations &
Parameters

Analysis

Conclusion

Beeler-Reuter Equation

Describe the electrical activity of cardiac myocytes

Background

Model

Equations &
Parameters

Analysis

Conclusion

Beeler-Reuter Equation

$$\frac{\partial V_m}{\partial t} = - \frac{I_{BR} + I_{ep} + I_{fu}}{C_m} + \nabla * (D_g * \nabla V_m) + \nabla * (D_g * \nabla \varphi_e)$$

φ_e : extra – cellular potential

D_g : intra – cellular diffusion of the electrical potential

C_m : capacitance per surface area of the myocyte

V_m : membrane potential

I_{ep} : current associated with electroporation

I_{BR} : membrane current

I_{fu} : current associated with possible anode break stimulation

ODEs Influencing PDE

$$\frac{\partial V_m}{\partial t} = -\frac{I_{BR} + I_{ep} + I_{fu}}{C_m} + \nabla \cdot (D_g \cdot \nabla V_m) + \nabla \cdot (D_g \cdot \nabla \varphi_e)$$

- Need to solve for each ODE
- Example:

$$I_{BR} = I_X + I_K + I_{Na} + I_s$$

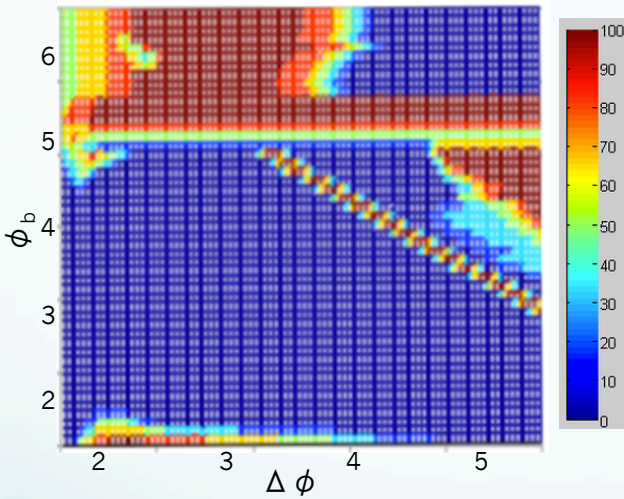
$$I_X = 0.8x \cdot \frac{e^{0.04(V+77)} - 1}{e^{0.04(V+35)}}$$

$$\frac{dx}{dt} = \frac{x_\infty - x}{T_x} \quad x_\infty = \frac{\alpha_x}{\alpha_x + \beta_x} \quad T_\infty = \frac{1}{\alpha_x + \beta_x}$$

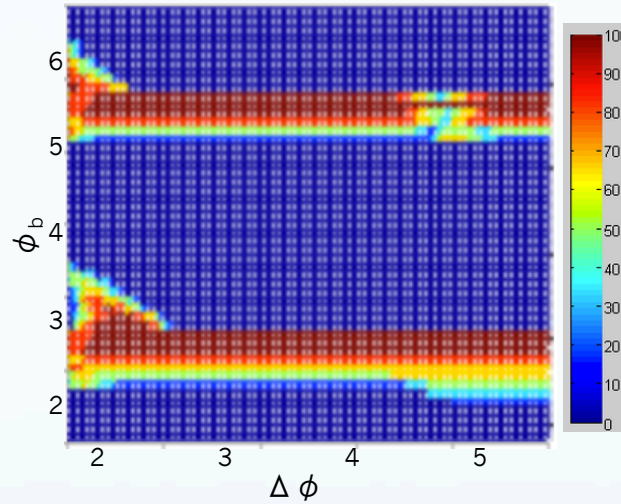
$$\alpha_x = \frac{0.0005e^{0.083(V+50)}}{1 + e^{0.057(V+50)}} \quad \beta_x = \frac{0.0013e^{-0.06(V+20)}}{1 + e^{0.04(V+20)}}$$

$E = 1 \text{ V/cm}$

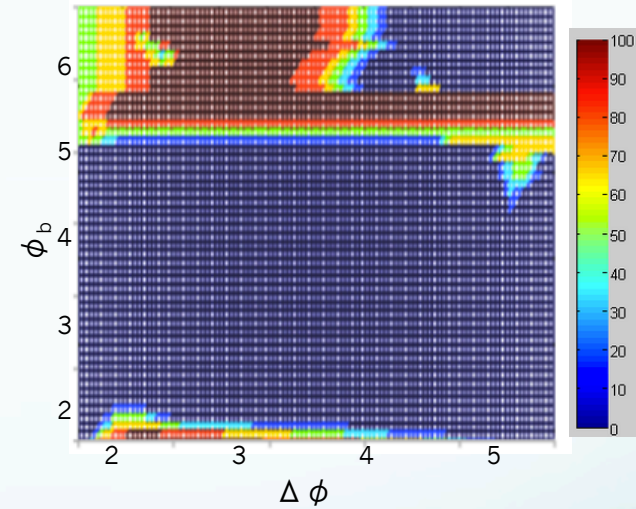
Monophasic



Symmetric Biphasic



Asymmetric Biphasic



Background

Model

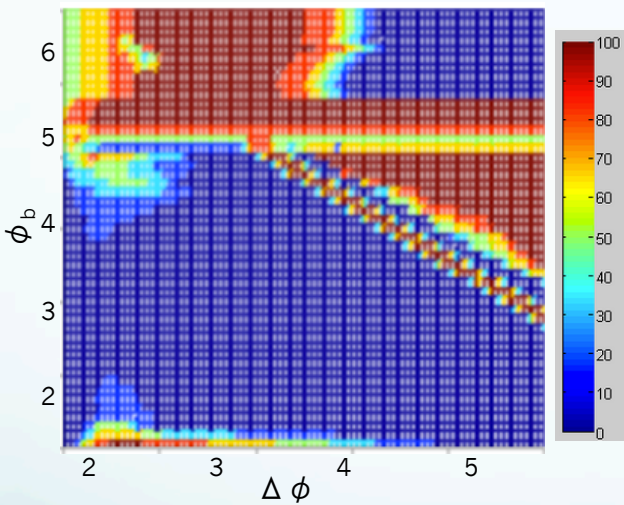
Equations &
Parameters

Analysis

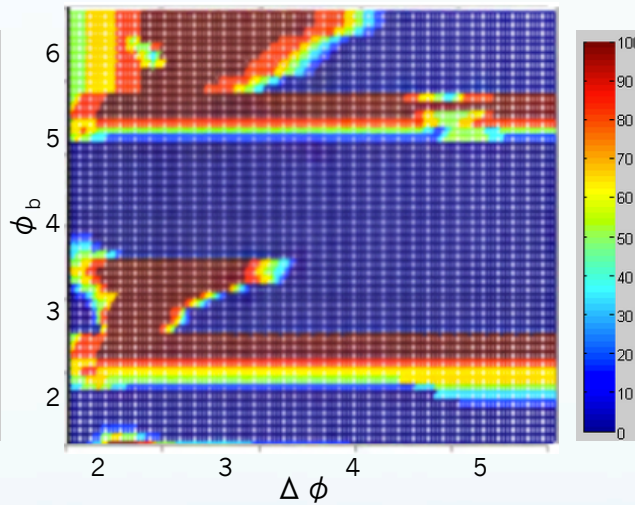
Conclusion

$E = 3 \text{ V/cm}$

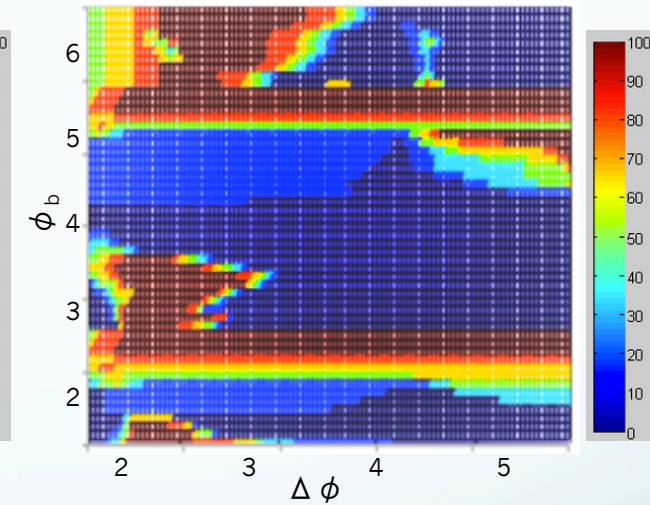
Monophasic



Symmetric Biphasic



Asymmetric Biphasic



Background

Model

Equations &
Parameters

Analysis

Conclusion

Protocol efficiency varies with shock energy

E (V/cm)	Monophasic	Symmetric Biphasic	Asymmetric Biphasic
1	28	17	16
3	44	43	45
7	93	99	98
9	99	100	100

Background

Model

Equations &
Parameters

Analysis

Conclusion

Conclusion



Monophasic is the most efficient at low energy



Asymmetric biphasic is the most efficient otherwise

Background

Model

Equations &
Parameters

Analysis

Conclusion

Conclusion

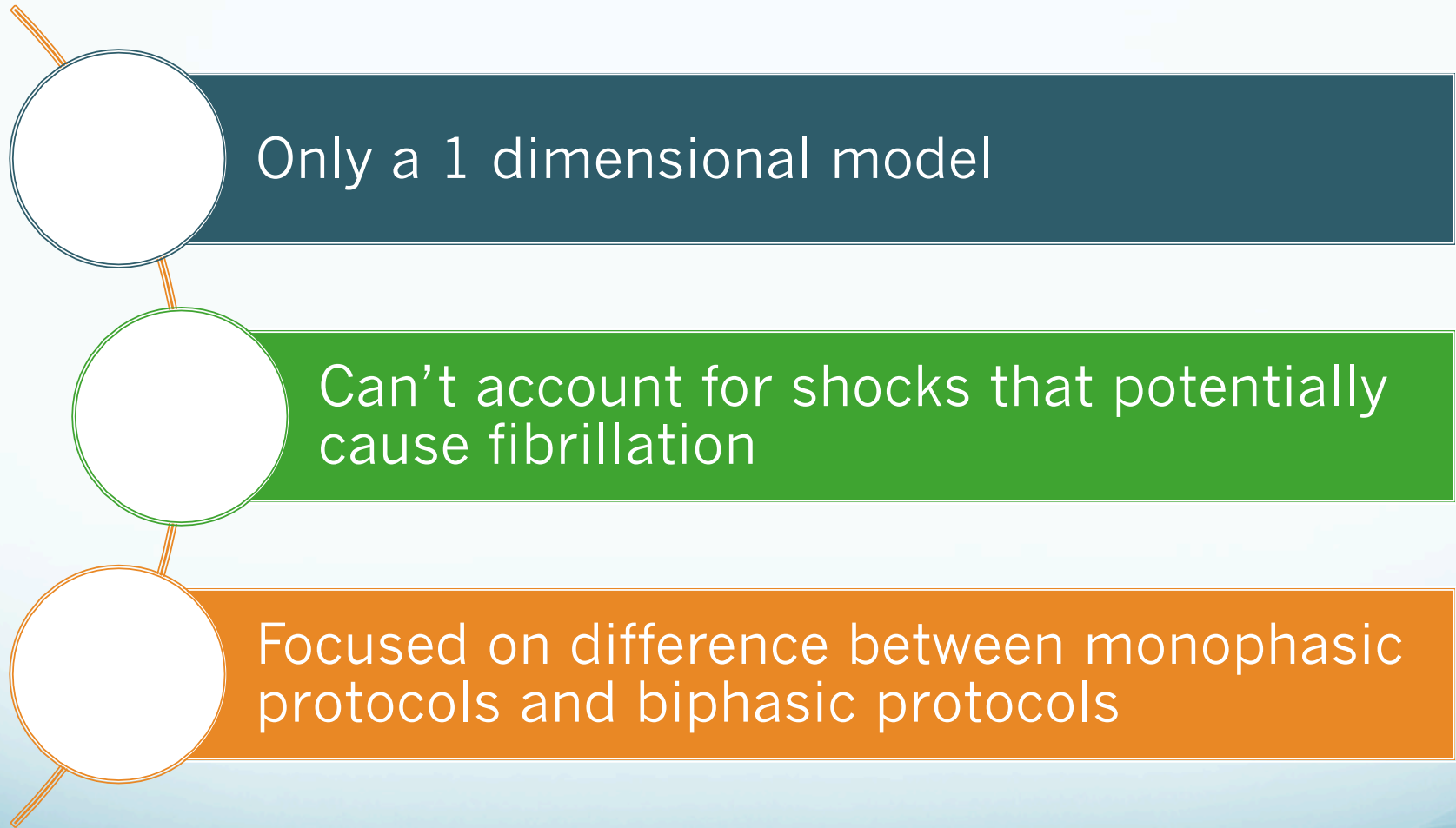
High E → 90% success

- The analysis of the numerical data shows that when the energy is high (which E is 7V/cm here) all of these three protocols will achieve 90% success

Efficiency

$Efficiency_{(biphasic_II)} > Efficiency_{(biphasic_I)} > Efficiency_{(monophasic)}$

Limitations



Background

Model

Equations &
Parameters

Analysis

Conclusion