

Spontaneous Synchronization in Power Grids

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Motivation

- Complex Power Grids
- Optimization
- Reliability



What is a Network?

- Generators
 - Nodes
- Transmission lines
 - Matrix
- What is synchronization

$$\dot{d}_1 = \dot{d}_2 = \dots = \dot{d}_n$$

Building the Grid

- Newton's Second Law

$$Ia = t$$

- Conservation of angular momentum

$$I \frac{d^2 d_i}{dt^2} = t_{mi} - t_{ei}$$

- Conservation of Energy

$$\frac{2H_i}{W_R} \frac{d^2 d_i}{dt^2} = P_{mi} - P_{ei} \quad H_i = \frac{1}{2} I W^2$$

Network Structure

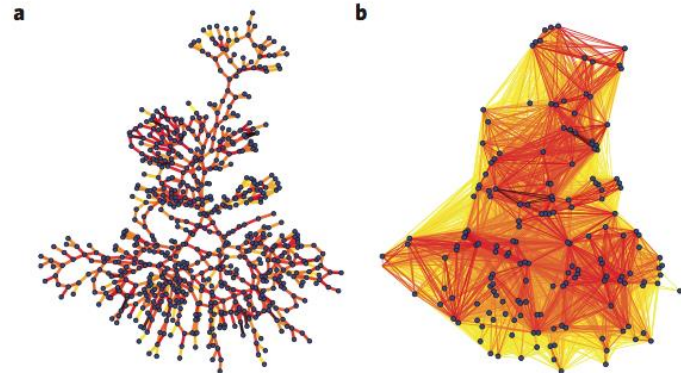
Assumptions?

Physical network vs Effective network

Admittance

$$Y = \frac{\bar{P}}{|V|^2}$$

$\mathbf{Y}_0 = (Y_{0ij})$: Y_{0ij} is the negative of the admittance between i and $j \neq i$



Stability condition from the swing equation

Assume

$$d_i = d_i^* + d_i'; \quad P_{ei} = P_{ei}^* + P_{ei}'; \quad P_{mi} = P_{mi}^* + P_{mi}'$$

$$\frac{2H_i}{W_R} \frac{d^2 d_i'}{dt^2} = \frac{\partial P_{mi}}{\partial W_i} W_i' - \frac{\partial P_{ei}}{\partial W_i} W_i' - \sum_{j=1}^n \frac{\partial P_{ei}}{\partial d_j} d_j'$$

Term 1: $\frac{\partial P_{mi}}{\partial W_i} / \frac{\partial P_{mi}}{\partial W_i} = -1 / (W_R R_i)$

Term 2: $\frac{\partial P_{mi}}{\partial W_i} / \frac{\partial P_{mi}}{\partial W_i} = D_i / W_R$

Term 3: $P_{ei}' = D_i W_i' / W_R + \sum_{j=1}^n E_i E_j (B_{ij} \cos d_{ij}^* - G_{ij} \sin d_{ij}^*) d_{ij}'$

Coupled 2nd Order Equations

$$X = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} \vec{d} \\ \overrightarrow{d} \end{bmatrix}$$

$$\dot{X} = \begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \end{bmatrix} = \begin{bmatrix} \vec{w} \\ \overrightarrow{w} \end{bmatrix}$$

$$\dot{X}_1 = X_2$$

$$\dot{X}_2 = -PX_1 - BX_2$$

Coupled 2nd Order Equations

$$B = \frac{1}{2H_i} + \frac{D_i}{2H_i}$$

B is the diagonal matrix of elements β

$$P_{ij} = \begin{cases} \frac{\omega_R E_i E_j}{2H_i} (G_{ij} \sin \delta_{ij}^* - B_{ij} \sin \delta_{ij}^*), & i \neq j \\ - \sum_{k \neq i} P_{ik}, & i = j \end{cases}$$

Simplifying coupled equations

$$\dot{Z}_j = \begin{pmatrix} a & 0 \\ c & -a_j \end{pmatrix} \begin{pmatrix} 1 \\ -b \end{pmatrix} \ddot{Z}_j, \quad Z_j = \begin{pmatrix} z \\ c \\ e \end{pmatrix} \begin{pmatrix} Z_{1j} \\ Z_{2j} \end{pmatrix} \begin{pmatrix} \ddot{0} \\ \ddot{\div} \\ \ddot{\emptyset} \end{pmatrix}$$

From the different equation, this has the solution

$$(\vec{X}_1)e^{l_1 t} + (\vec{X}_2)e^{l_2 t}$$

How we guarantee stabilities?

By ensuring the REAL part is negative in both terms

Finding Stability from Matrix

- From ODE's, we can find requirements for stability.
- Lyapunov Exponents

$$l_{j\pm} = -\frac{b}{2} \pm \frac{1}{2} \sqrt{b^2 - 4a_j}$$

Keeping λ Negative

- Need to keep all $\text{Re}(\lambda) < 0$
- Alter function to $\Lambda = \max (\text{Re} (\lambda)) \leq 0, j \geq 2$
- $J=1$ is a null eigenvalue
 - Related to shift in all phases
- How can we tune variable α to keep λ negative?

Function Behavior

- For $\alpha < 0$
 - $\Lambda > 0$, not usable
- For $\alpha > 0$
 - $\Lambda < 0$, usable and decreases for increasing α
- For $0 \leq \alpha \leq \beta^2/4$
 - Λ reaches minimum at $\alpha = \beta^2/4$
 - Imaginary part is added past this value

What value for α ?

- α is based on eigenvalues of the matrix P
- It is dependent on properties of the generator in the system
- We want the smallest non-zero value of α
 - This will increase stability
 - Choose α_2
 - α_1 is null, we ignore this value

Parameters for changes in demand

$$b = b_{opt} \circ 2\sqrt{a_2}$$

- Droop Parameter (Off-line optimization)

$$R_i = \frac{1}{4H_i\sqrt{a_2} - D_i} \quad i = 1, \dots, n$$

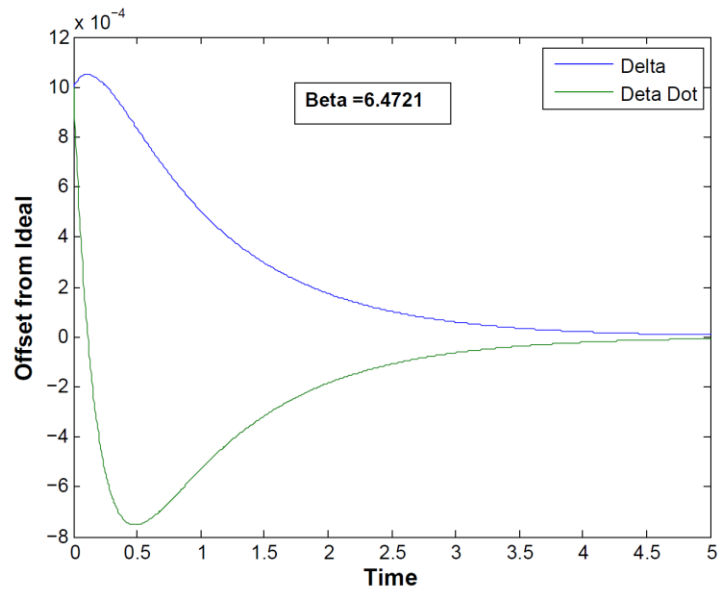
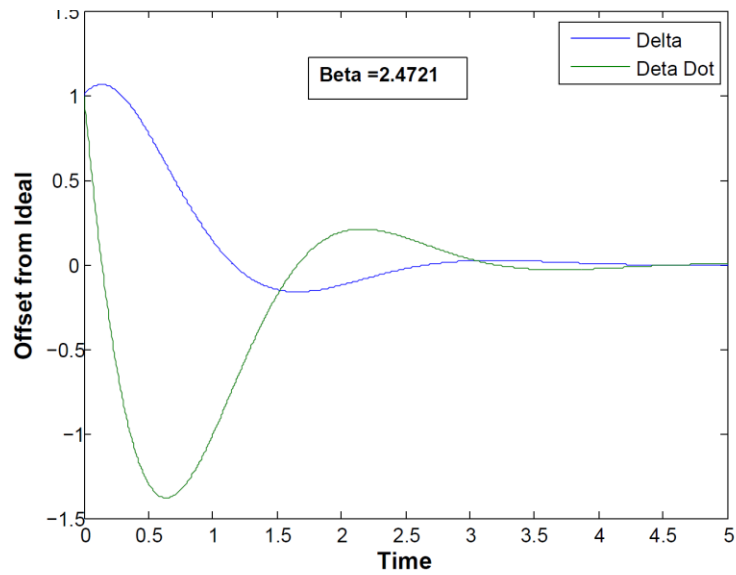
- Damping Coefficient (Online optimization):

$$D_i = 4H_i\sqrt{a_2} - \frac{1}{R_i}, \quad i = 1, \dots, n$$

Testing Methods

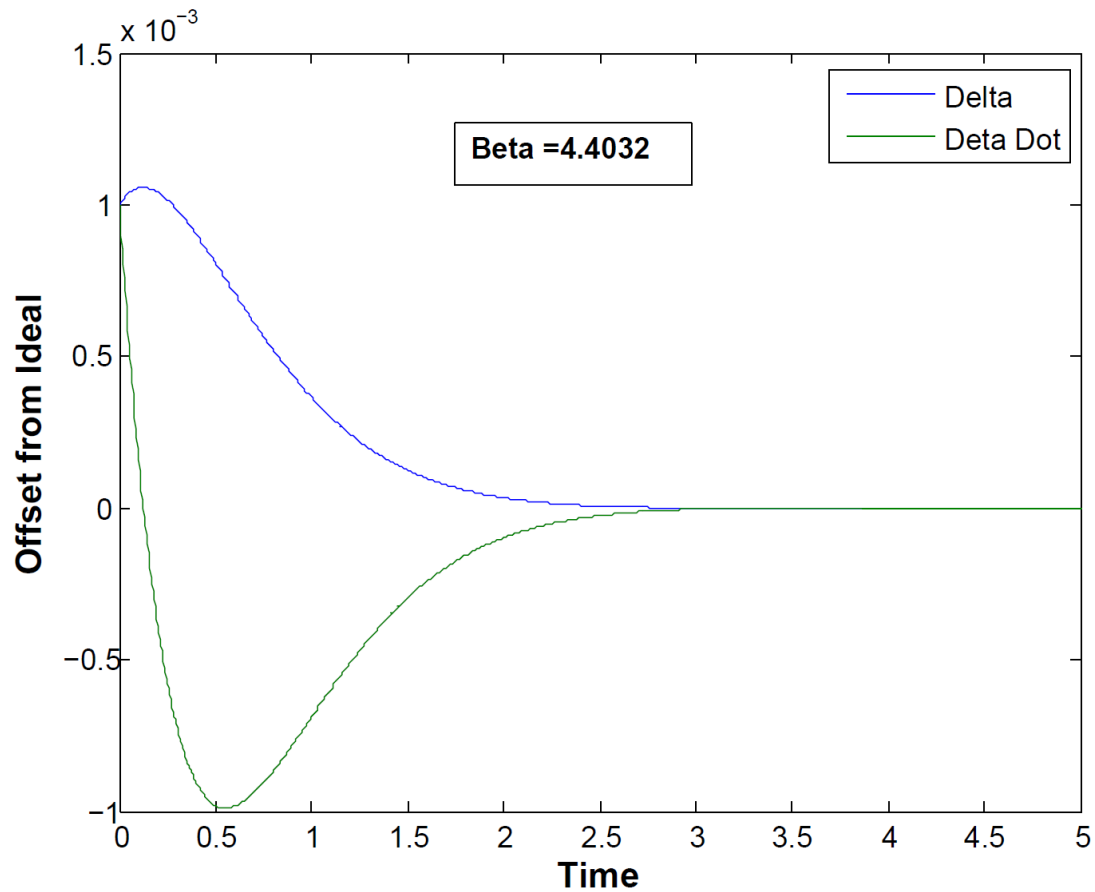
- MATLAB script written from a simplified coupled equations.
- Assumed β equal for all nodes
- Arbitrary values for α
- 5 node system
- Solved using ODE45 function
- Integrated δ solution for varying β
- Repeated multiple times

Test Results

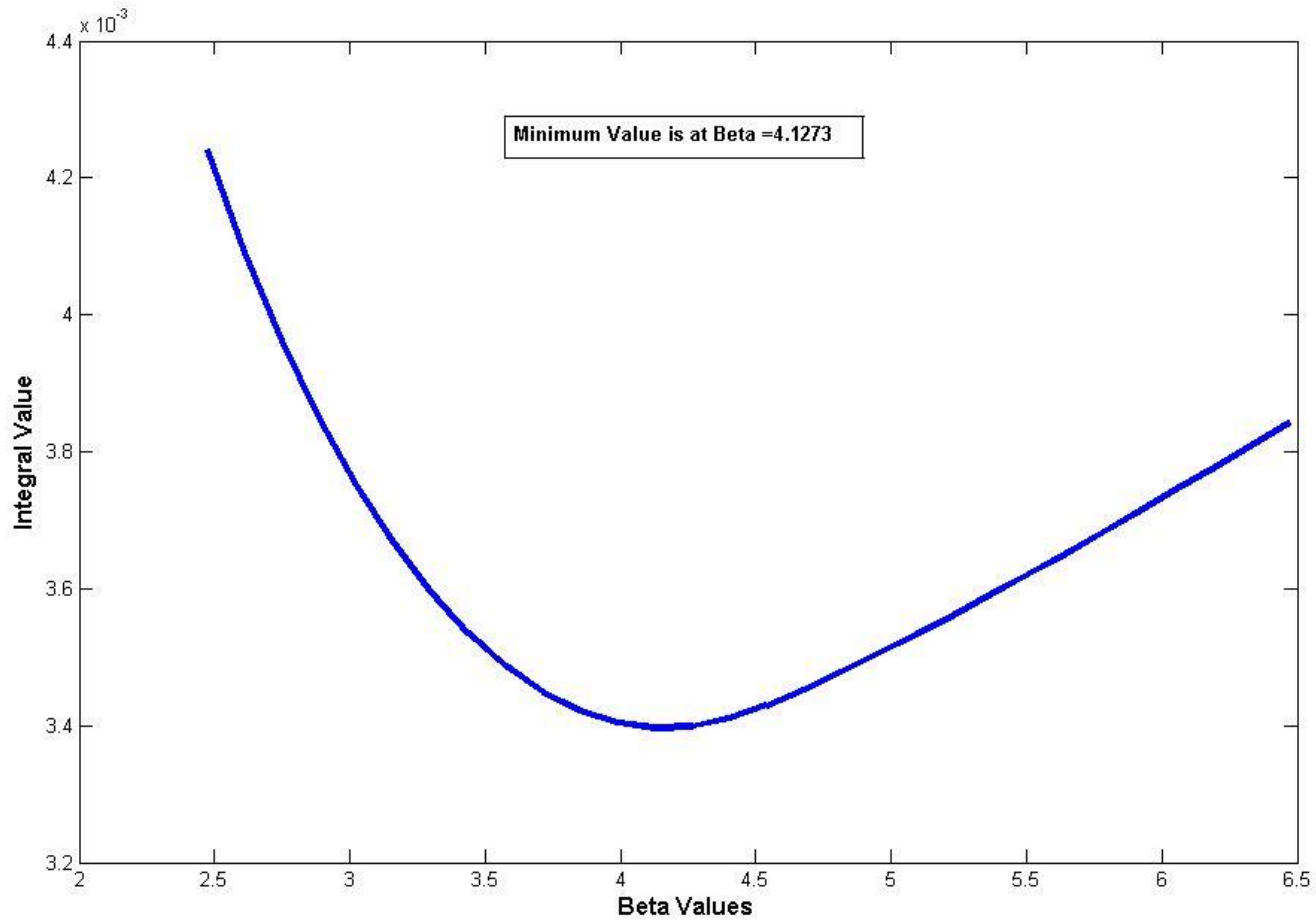


Test Results

- Optimal Beta



Test Results



Conclusions

- Optimal Beta differs slightly from the expected value from the literature
- Can be explained by the randomness added to alpha values
- Within 10% range

Questions?