## Search for a car parked on a forest road

Math 485 Midterm Presentation March 11, 2014

Mentor: Zhelezov, Gleb

Members: Rickel, Jayson Anthony Nguyen, Alex Braun, Rachel Anne Alabkari, Mohammed Gong, Yu



### Outline

- Reference and link
- Abstract
- Introduction
- Mathematical Model
- Theoretical Calculations
- Monte Carlo Method
- Preliminary Simulation Results
- Conclusion
- Future work



Reference and link

#### Yu Baryshnikov and V Zharnitsky, Search on the brink of chaos, Nonlinearity, 25 (2012), 3023-3047, <u>doi:10.1088/0951-7715/25/11/3023</u>



#### Abstract

#### Overall Goal:

The analysis of a linear search problem for an object placed from a given probability density function using analytical and numerical methods.

Our Current Project:

The development of numerical methods simulating the search for an object placed using an exponential distribution function and the minimization of the search for the object.



#### Search for a Parked Car on a Forest Road

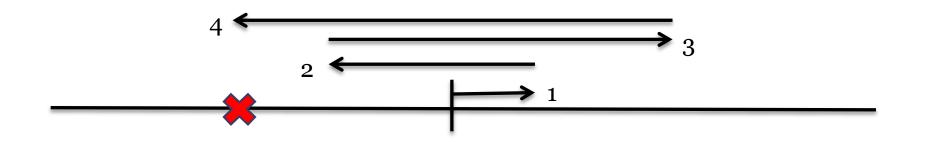




#### Introduction

The traditional linear search problem:

- An object is placed on a line using a given probability density
- Using an initial step length, the searcher goes back and forth according to step lengths given by a specific formula





#### How to model the problem

- Why do we need a model?
- Can help to predict the position of a car (Probability distribution).
- 2. The prediction of mathematical model can help to save time and find the best cost for traveler (Minimizing problem).
- 3. Then lead the real world competition to better behavior (Modeling problem)

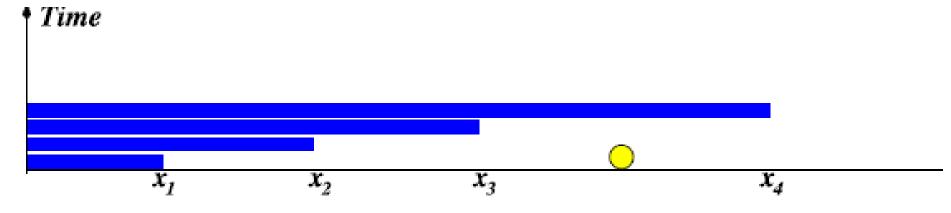


#### Mathematical Model

#### **Variables**

L(x, H): the total distance travelled until the point H is found in function of x

 $E(x) = \mathbb{E}[L(x, H)]$ : the cost of the search plan x



F(x): chosen probability density function



#### Mathematical Model

Let us consider:

- Hamiltonian dynamics model on the half-line  $\mathbb{R}_+$
- Homogeneous tail distribution function or Pareto distribution is differentiable
- If the plan x is optimal, then the term  $\{x_k\}$  satisfy the variational recursion, where f(x) is the cumulative density function of the distribution

$$x_n = -\frac{f(x_{n-2})}{f'(x_{n-1})}$$

If we find  $x_1$  and  $x_2$ , we can optimally define the rest of the sequence

• For example, the optimal cost of a plan, where  $F(x) = x^{-b}$ , is given by

$$E(x) = \sum_{k=1}^{\infty} x_k f(x_{k-1})$$





We are attempting to minimize the expectation for the cost function for the total length of the search (EL).

 $\mathsf{EL} = \int_0^\infty \mathsf{F}(\mathsf{x}) \mathsf{L}(\mathsf{x}) \mathsf{d}\mathsf{x}$ 

Where L(x) = 
$$\begin{cases} 2x_1 & 0 < x \le x_1 \\ 2(x_1 + x_2) & x_1 < x \le x_2 \\ & \dots & \\ 2\sum_{i=1}^N x_i & x_{N-1} < x \le x_N \end{cases}$$



#### Theory

$$EL = \int_0^{x_1} 2x_1 F(x) dx + \int_{x_1}^{x_2} 2(x_1 + x_2) F(x) dx + \dots + \int_{x_{N-1}}^{x_N} 2\sum_{i=1}^N x_i F(x) dx$$

CDF:  $f(x) = \int_0^x F(x) dx$ 

 $\mathsf{EL} = 2\mathsf{x}_1[\mathsf{f}(\mathsf{x}_1) - \mathsf{f}(\mathsf{x}_0)] + 2\mathsf{x}_1[\mathsf{f}(\mathsf{x}_2) - \mathsf{f}(\mathsf{x}_1)] + 2\mathsf{x}_2[\mathsf{f}(\mathsf{x}_2) - \mathsf{f}(\mathsf{x}_1)] + \dots$ 

$$EL = 2[\sum_{n=1}^{\infty} x_n - \sum_{m=2}^{\infty} x_m f(x_{m-1})]$$



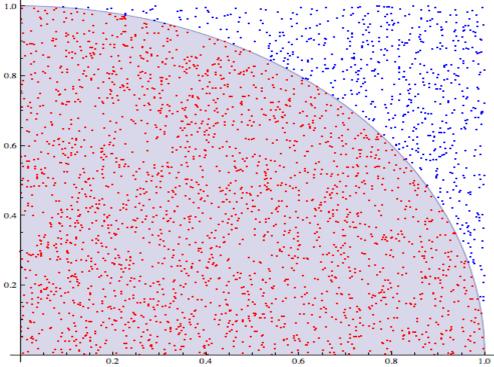
#### Monte Carlo Method

Many random samplings to obtain numerical ...

For our purposes:

- Select placement of the car based on the probability density
- Determine the total cost to find car
- Average all lengths to find the expected value
- Find ideal pivots based on the comparison of many different expected values

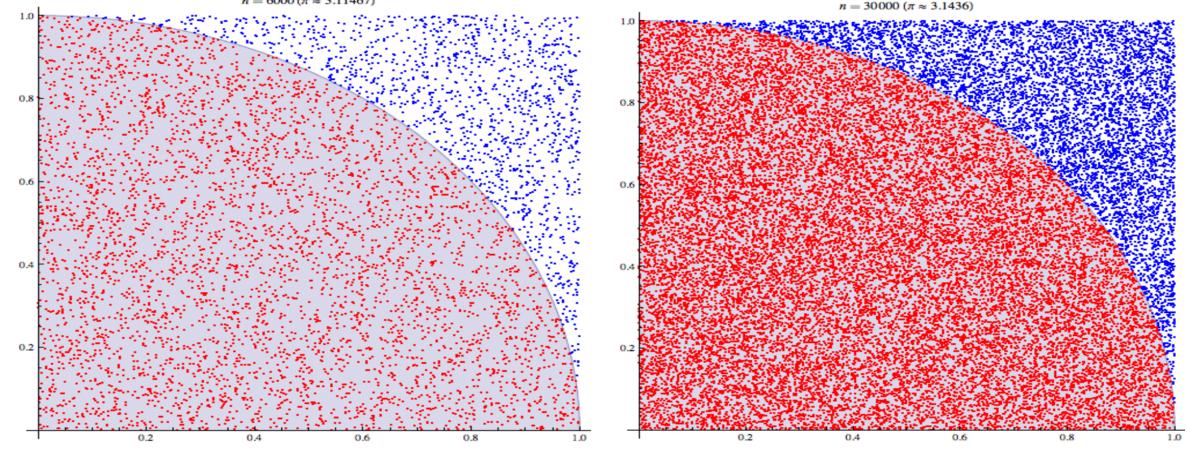
#### $n = 3000 \, (\pi \approx 3.16667)$



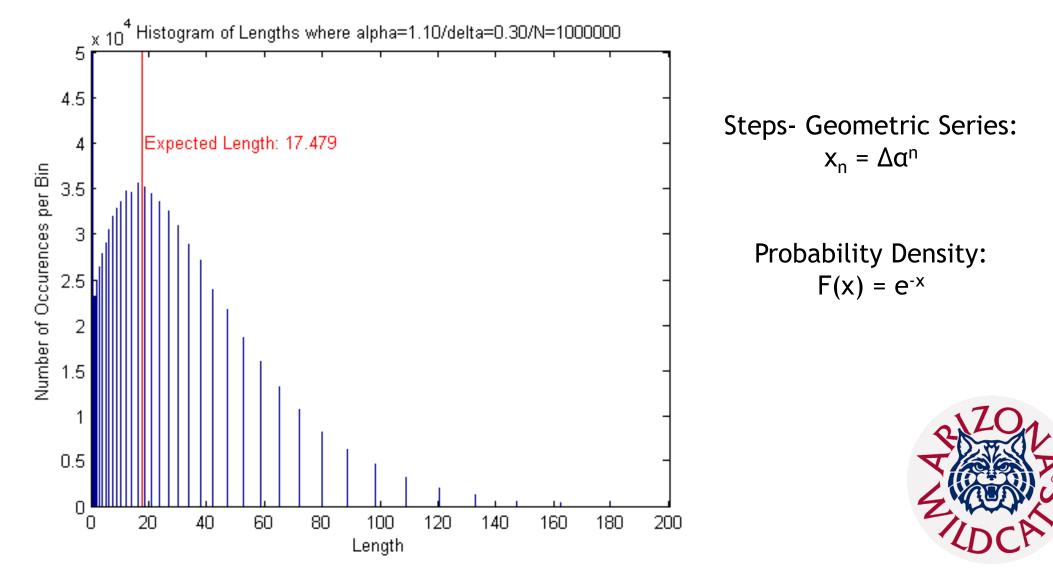


#### Monte Carlo Method Example

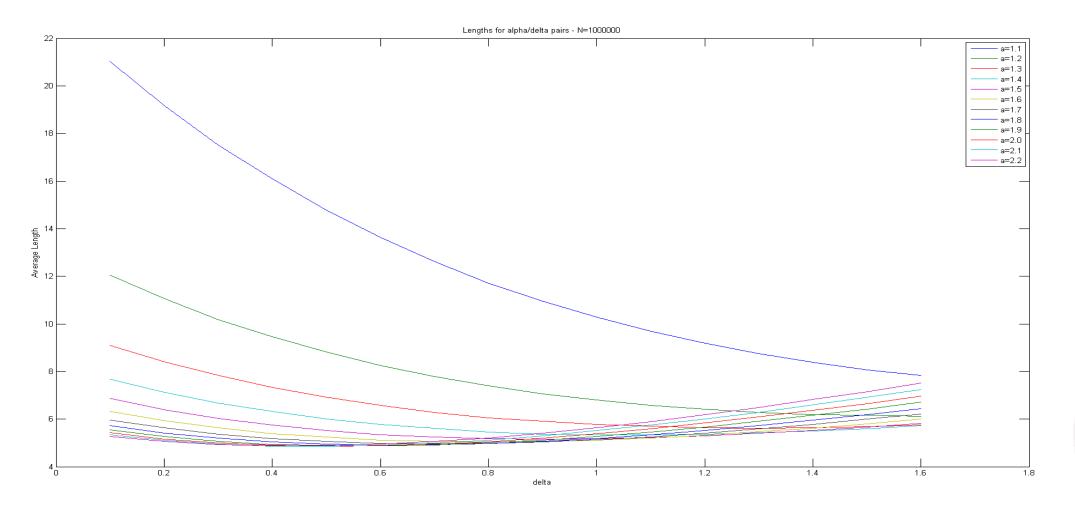
 $= 6000 (\pi \approx 3.11467)$ 



#### **Preliminary Simulations**



#### Preliminary Simulations Optimal -> $\alpha$ = 2.1 ; $\Delta$ = 0.5 ; L = 4.7932





#### Conclusion

- We know that the expectation of the length converges
- We cannot find the value analytically
- Use numerical methods and Monte Carlo simulations to find expectation length



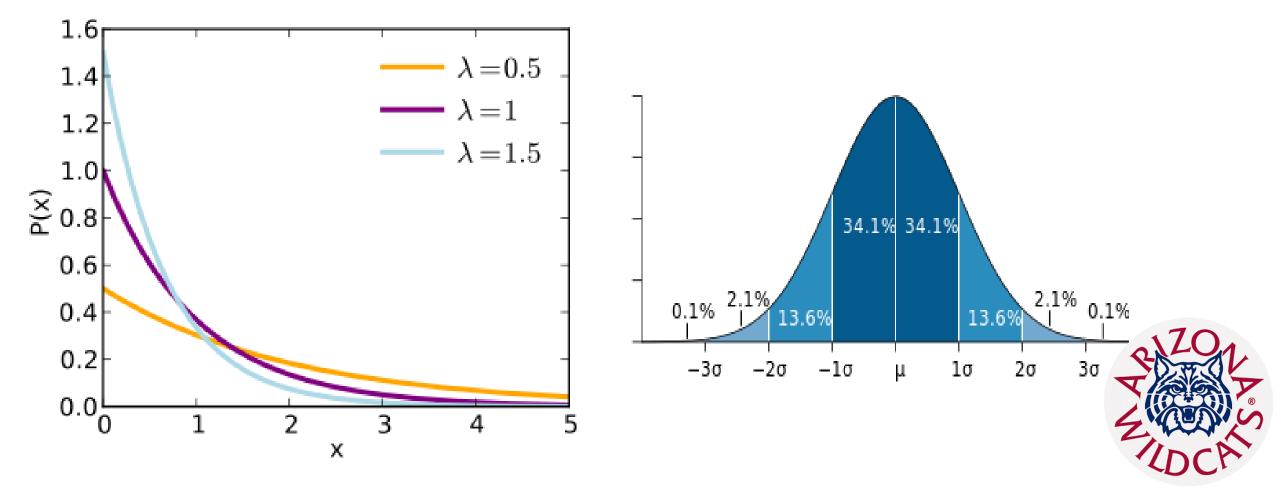
#### Future work

- Repeat problem for different distributions
- Find E(x)
- Find optimal  $x_1$  and  $x_2$  via numerical simulations
- Monte Carlo Simulations
- Random Steps
- Road has a known, finite length



#### **Distributions to Consider**

**Exponential Distribution** 



Normal/Gaussian Distribution

#### **Distribution Equations**

**Exponential Distribution** 

#### Normal/Gaussian Distribution

$$f(x:\lambda) = \begin{cases} \lambda e^{-\lambda x} ; x \ge 0\\ 0 ; x < 0 \end{cases}$$

$$f(x,\mu,\sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$



# Questions?

