

Lecture 6

In the

last lecture we derived the KDV equation

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Equations (5.32) and (5.44). Therefore we will assume

simplest ~~ratio~~ mentioned

$$\frac{\partial u}{\partial t} = 0 \text{ and } \frac{\partial \psi}{\partial t} = 0$$

and the corresponding Vries equation

$$(6.1)$$

$$u_x + 6u u_x + u_{xxx} = 0$$

As per (2.1) as

$$u = f(x)$$

we satisfy to

$$u \approx 0 \text{ (5.4)}, \text{ where } \psi$$

Equations

$$(6.2)$$

$$L\psi = -\lambda^2 \psi$$

$$\frac{\partial \psi}{\partial t} + M_0 \psi = 0$$

remember that

$$L\psi = \frac{\partial^2 \psi}{\partial x^2} + u\psi$$

$$(6.3)$$

$$M\psi = \lambda \frac{\partial \psi}{\partial x} + 6u \frac{\partial \psi}{\partial x} + 3u_x \psi$$

~~As per (2.1) as~~ the transitioned Lax representation

This is exactly the KDV equation

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The standard way to construction exact solutions of leads through development of the sectoring theory for the Schrodinger equation (6.2). We will do this through the use of the dressing method which makes it possible to find more straightforward way

The condition  $\frac{\partial T}{\partial \eta} = 0$  means the T satisfies

To equation  $(k^2 - \eta^2)T(\lambda, \eta) = 0$  hence  $-2i\eta$   $f(-\lambda, -\bar{\lambda})$

$$T(\lambda, \bar{\lambda}, \eta, \bar{\eta}) = R(\lambda, \bar{\lambda}) e^{-2i\eta} f(-\lambda, -\bar{\lambda}) \quad (6.4)$$

or  $\frac{\partial \psi}{\partial \bar{\lambda}} = f(-\lambda, -\bar{\lambda}) R(\lambda, \bar{\lambda}) e^{-2i\eta}$   $\varphi = \lambda x + 4\lambda^3 t$

Here  $R(\lambda, \bar{\lambda})$  — the dressing function is still is a free functional parameter

Remember that

$$\psi \rightarrow \lambda + \frac{k_0}{\lambda} + \dots$$

$$u = -2i \frac{\partial \psi}{\partial x} \quad (6.5)$$

Let  $\lambda_n = i\kappa_n$  — complex numbers placed on the imaginary axis such that

$$\Re \lambda_n + \Im \lambda_n \neq 0 \tag{6.4}$$

We will seek solution of the  $\bar{D}$ -problem in the form

$$f = 1 + i \sum_{n=1}^N \frac{\lambda_m}{\lambda - i\kappa_m} \tag{6.5}$$

Then

$$f_0 = i \sum_{n=1}^N \lambda_n \quad \mathcal{L} = \mathcal{R} \frac{\partial f_0}{\partial x} = \mathcal{R} \frac{\partial}{\partial x} \sum_{n=1}^N \lambda_n \tag{6.6}$$

and

$$f(\cdot, \lambda) = 1 - i \sum \frac{\lambda_m}{\lambda + i\kappa_m}$$

Evaluation of this function to the point  $\lambda = i\kappa_n$

gives

$$f(i\kappa_n) = 1 - \sum \frac{\lambda_m}{\lambda_m + \lambda_n}$$

Calculation of the derivative  $\mathcal{R} \bar{\lambda}$  gives

$$\frac{\partial Y}{\partial X} = \pi i \sum Y_m \delta(\lambda - i\alpha_m) \delta(\bar{\lambda} + i\alpha_m) \quad (6.5)$$

To match (6.5) with (6.4), one must choose ~~choose~~ (6.7)

$$R(\lambda, \bar{\lambda}) = \pi \sum C_n \delta(\lambda - i\alpha_n) \delta(\bar{\lambda} + i\alpha_n) \quad \text{the}$$

Collecting all together we and up with the

System of equations

$$R_n Y_n + C_n e^{-2\varphi_n} \sum_{m=1}^N \frac{Y_m}{\alpha_n + \beta_m} = C_n e^{2\varphi_n} \quad (6.5')$$

$$\varphi_n = \alpha_n X + 4 \alpha_n^3 t$$

Now

$$Y_n = e^{-\varphi_n} \psi_n$$

$$\psi_n + C_n e^{\varphi_n} \sum \frac{Y_m e^{-(\varphi_n + \varphi_m)}}{\alpha_n + \beta_m} = C_n e^{\varphi_n} \quad (6.6)$$

Now

$$u = 2 \frac{d}{dx} \sum \psi_n e^{\varphi_n} \quad (6.7)$$

System (6.5) and (1.6) have identical determinants which will be called  $\Delta$ .  $2^{pn}$   
 Let us denote  $\sum_n = \frac{C_n}{2^n}$

For  $N=2$

$$\Delta = 1 + \sum_1 + \sum_2 + \sum_1 \sum_2 \frac{(x_1 - x_2)^2}{(x_1 + x_2)^2}$$

(6.7)

For  $N=3$

$$\Delta = 1 + \sum_1 + \sum_2 + \sum_3 + \sum_1 \sum_2 \frac{(x_1 - x_2)^2}{(x_1 + x_2)^2} + \sum_1 \sum_3 \left( \frac{x_1 - x_3}{x_1 + x_3} \right)^2 + \sum_2 \sum_3 \left( \frac{x_2 - x_3}{x_2 + x_3} \right)^2 + \sum_1 \sum_2 \sum_3 \left( \frac{x_1 - x_2}{x_1 + x_2} \right)^2 \left( \frac{x_1 - x_3}{x_1 + x_3} \right)^2 \left( \frac{x_2 - x_3}{x_2 + x_3} \right)^2$$

This is a hint for construction of the determinant. It consists of  $2^N$  terms. The first is 1, the last one is  $\prod_{i \neq j} \left( \frac{x_i - x_j}{x_i + x_j} \right)^2$

According to the Kronecker rule the solution of  $n$ -th term's system  $\Delta_n$

$$\Delta_n = \frac{A_n}{\Delta} \text{ column is replaced to } \begin{pmatrix} c_1 e^{p_1} \\ \vdots \\ c_n e^{p_n} \end{pmatrix}$$

According to (1.7)

$$u = a \frac{d}{dx} \sum_{n=1}^N e^{-\varphi_n} \frac{A_n}{A}$$

However, one can easily realize that

$$\sum e^{-\varphi_n} A_n = \frac{dA}{dx}$$

Remarkable result

Finally we obtain

$$(1.8)$$

$$u = a \frac{d^2}{dx^2} \ln A$$

conceal the reality

This formula astonishing property.

Next we replace

$$x + ct + c$$

$$(5.10)$$

$A \rightarrow \tilde{A} = A e^{g_1 x + g_2 t + c}$  - arbitrary constants

then  $\frac{d^2}{dx^2} \ln \tilde{A} = \frac{d^2}{dx^2} \ln A$

Transformation (5) does not change the solution of KDV! We will use this property generously