

# Calculus and Differential Equations I

MATH 250 A

Differential equations of the form  $y' = g(x)$

## Formal solutions

- The differential equation  $y' = g(x)$ , where  $g$  is continuous, may formally be **solved by integration**, so that

$$y(x) = \int g(x) dx + C.$$

- Fundamental theorem of Calculus:** if  $f$  is a continuous function on  $[a, b]$  and if  $f(x) = F'(x)$ , then

$$\int_a^b f(x) dx = F(b) - F(a).$$

- Second fundamental theorem of Calculus:** if  $f$  is continuous on  $[a, b]$  and if  $x \in [a, b]$ , then

$$\frac{d}{dx} \int_a^x f(t) dt = f(x).$$

## Formal solutions (continued)

- We can therefore write the **general solution** to  $y' = g(x)$  as

$$y(x) = \int_a^x g(t) dt + C.$$

- If we can **find an antiderivative** of  $g(x)$ , then we have an **explicit solution**.
- Given a continuous function  $g$ , can we always find an **explicit** expression for an antiderivative of  $g$ ?
  - Yes
  - No
- There exists functions which we do not know how to integrate. An example is the **error function**

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x \exp(-t^2) dt.$$

## Formal solution (continued)

- Even if we do not know how to integrate  $g$ , we may still be able to say something about the behavior of  $y(x)$  by looking at **properties** of the antiderivative of  $g$ .
- As  $x \rightarrow \infty$ , the integral in the expression for  $y$  becomes an **improper integral** of the form  $\int_a^\infty g(t) dt$ . We will study improper integrals in the second semester of this course.
- An **initial or boundary condition** of the form  $y(x_0) = y_0$  allows us to pick a **particular solution** from the **one-parameter family** of solutions:

$$y(x) = \int_{x_0}^x g(t) dt + y_0.$$

- A **solution curve** is the graph of a particular solution  $y(x)$ .

## Existence and uniqueness of solutions

- **True/False:** All solution curves of  $y' = g(x)$  may be obtained by vertical translation of one of them.
  - 1 True
  - 2 False
- Since we assume that  $g$  is continuous, we know that **solutions exist**. Are they **unique**?
- If there is a **unique solution** for any initial condition, is it possible for solution curves to **cross (or meet)** at a point?
  - 1 Yes
  - 2 No
- If at some point  $g$  becomes **singular**, e.g. if it is undefined or it stops being continuous, the **argument for existence**, which assumes that  $g$  is continuous, **will fail**.
- Nevertheless, in some cases it will be possible to **patch** solutions of a differential equation found in adjacent intervals.

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## Qualitative properties of solutions

- Since we know  $y'$ , and assuming that  $g$  is smooth, we know **all of the derivatives** of  $y$ .
- As a consequence, we know when the solution  $y$  is **increasing or decreasing**, and we know the **concavity of the graph of  $y$** .
- We can **use symmetries of the equation** to relate a solution to another solution. For instance, if  $y(x)$  is a solution and  $g(x)$  is odd, then  $u(x) = y(-x)$  is also a solution.
- If  $y(x)$  is a solution and  $g(x)$  is even, then which of the solutions below is also a solution?
  - 1  $u(x) = y(-x)$
  - 2  $u(x) = -y(-x)$
  - 3 None of the above
- Note that symmetries tell you about properties of the **family of solutions**, not of each particular solution.

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## Example of application

Consider the differential equation  $y' = \frac{x^2 + 1}{x^2 - 1}$ .

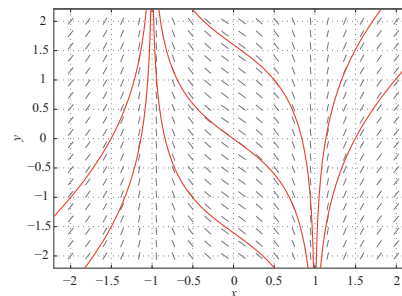
- **True/false:** Solution curves increase for  $x$  in  $(-1, 1)$ .
  - 1 True
  - 2 False
- **True/false:** Solution curves are concave up for  $x \geq 0$ .
  - 1 True
  - 2 False
- **True/false:** Isoclines are all parallel to the  $y$ -axis.
  - 1 True
  - 2 False
- **True/false:** The family of solution curves is symmetric with respect to the  $y$ -axis.
  - 1 True
  - 2 False

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## Slope fields

A **slope field** for the differential equation  $y' = g(x)$  is a collection of line segments in the  $(x, y)$  plane such that the slope of the segment centered at point  $(x, y)$  is equal to  $g(x)$ .



Slope field for the differential equation  $y' = \frac{x^2 + 1}{x^2 - 1}$ , plotted with the program PPLANE.

- Given an **initial condition**  $y(x_0) = y_0$ , one can **sketch the associated solution curve** (assuming it exists and is unique) by following the slope field, starting from  $(x_0, y_0)$ .
- You should enter the **slope field** program into your calculator. In class, we will use PPLANE to plot slope fields.

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## Some of your questions

### Uniqueness

- Why is it important?
- Can we see an example of a differential equation for which solutions are not unique?
- Are singularities in  $g(x)$  related to uniqueness issues?
- How is uniqueness related to non-intersecting solution curves?

## Some of your questions (continued)

### Solutions

- Do differential equations always have an infinite number of solutions?
- If so, do they always differ by a constant?
- How do we know when a differential equation cannot be solved?
- What happens to solutions of  $y' = g(x)$  as  $x$  goes to infinity?
- Can an explicit solution have a vertical tangent?
- If  $g(x)$  has a vertical tangent at  $x_0$ , does it mean that if one solves  $dx/dy = 1/g(x)$ , one would have a horizontal tangent at that point?
- If we solve  $dy/dx = g(x)$  and  $dx/dy = 1/g(x)$ , do we get the same solution curves?

## Some of your questions (continued)

### Slope fields

- How far in  $x$  and  $y$  should we go?
- How far apart should the points in the  $x$ - $y$  plane be?
- What do isoclines mean?
- Why are slope fields useful / necessary?
- How do we identify a singularity in a slope field?
- If there exists isoclines of infinite slope, can one construct a solution that spans both sides of the isocline?
- Why can't we just use slope fields to solve ode's?