


Calculus and Differential Equations I










MATH 250 A

Summary

What differential equations are and how we study them







- **Examples** of differential equations and of systems of differential equations.
 - Identify the **independent** and **dependent variables**, as well as the **parameters**, if any.
 - **Characteristic properties**: order, linear vs. nonlinear, autonomous vs. non-autonomous.
 - **Initial or boundary conditions** are often given.
- **Questions** to be addressed in the study of a differential equation (or a system of differential equations)
 - Existence and uniqueness
 - Geometric considerations
 - Numerical solutions
 - Analytical solutions





Existence and uniqueness

- **Question:** Given an initial condition, decide whether there **exists** a solution **near the initial condition**, and if so, whether it is **unique**.
- We have seen a variety of **theorems** that guarantee existence and/or uniqueness of solutions to differential equations.
 - For equations of the form $y' = g(x)$   
 - For equations of the form $y' = g(y)$  
 - For equations of the form $y' = g(x, y)$  
 - For first order linear equations  

















▶ Back

Geometric considerations

- Decide where solution curves increase, decrease, or are concave up or down
 - For equations of the form $y' = g(x)$   
 - For equations of the form $y' = g(y)$   
 - You should be able to generalize the above to equations of the form $y' = g(x, y)$






















- Symmetries of the **family of solution curves** \mathcal{S} given    
symmetries of the differential equation \mathcal{E}
 - If \mathcal{E} is invariant under $x \rightarrow -x$, then \mathcal{S} is symmetric with respect to the y -axis.
 - If \mathcal{E} is invariant under $y \rightarrow -y$, then \mathcal{S} is symmetric with respect to the x -axis.
 - If \mathcal{E} is invariant under $x \rightarrow -x$ and $y \rightarrow -y$, then \mathcal{S} is symmetric with respect to the origin.

Numerical solutions

- For equations of the form $y' = g(x)$, we have seen various ways of **approximating integrals**.   
- For equations of the form $y' = g(x, y)$, we have discussed **Euler's method**.    
- In both cases, we can sometimes decide whether an approximation is an **underestimate or overestimate**.  
- We also discussed the various **approximation errors** associated with these methods.   
- As part of the above, we introduced **Taylor polynomials** as ways to approximate functions and discussed the resulting **error**.    

▶ Back

Analytical solutions

- For equations of the form $y' = g(x)$  
- For equations of the form $y' = g(y)$   
- For equations of the form $y' = g(x, y)$ 
 - Separable equations 
 - Equations with homogeneous coefficients  
 - Linear equations  
 - Bernoulli equations  
- Solving a differential equation always involves evaluating an integral. We have seen various **methods of integration**
 - Substitutions  
 - Integration by parts  
 - Method of partial fractions    
 - Trigonometric substitutions 