

## Linear systems (continued)

### 3. Classification of the origin as a fixed point

We are interested in systems of the form

$$Y' = M Y$$

where  $Y = \begin{bmatrix} x \\ y \end{bmatrix}$  and  $M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$

2x2 with constant coefficients

Eigenvalues of  $M$  solve the characteristic equation

$$\lambda^2 - \lambda \operatorname{Tr}(M) + \det(M) = 0$$

Recall that if  $\lambda_1$  &  $\lambda_2$  are roots of the above equation, then

$$\begin{aligned} \lambda^2 - \lambda \operatorname{Tr}(M) + \det(M) &= (\lambda - \lambda_1)(\lambda - \lambda_2) \\ &= \lambda^2 - \lambda(\lambda_1 + \lambda_2) + \lambda_1 \lambda_2 \end{aligned}$$

$$\begin{aligned} \text{So } \operatorname{Tr}(M) &= \lambda_1 + \lambda_2 \\ \det(M) &= \lambda_1 \lambda_2 \end{aligned}$$

We want to describe the trajectories of  $Y' = M Y$  in the vicinity of the origin, which is a fixed point. (Origin is the same as  $Y = 0$ ).

### 1. Real roots $\text{Tr}(M)^2 - 4 \det(M) > 0$

\* Roots of same sign:  $\det(M) > 0$

Both roots negative:  $\text{Tr}(M) < 0 \rightarrow$  sink

" positive:  $\text{Tr}(M) > 0 \rightarrow$  source

\* Roots of opposite signs:  $\det(M) < 0$

### 2. Complex roots $\text{Tr}(M)^2 - 4 \det(M) < 0$ , $\det(M) > 0$

Recall the roots are complex conjugate of one another since  $M$  has real entries.

\*  $d = \alpha \pm i\beta$   $\alpha \neq 0$

$\alpha > 0$  unstable spiral  $\text{Tr}(M) > 0$

$\alpha < 0$  stable spiral  $\text{Tr}(M) < 0$

\*  $d = \pm i\beta$  center  $\text{Tr}(M) = 0$

### 3. Degenerate cases

Double (real) root.  $d_1 = d_2 = d$   $\text{Tr}(M)^2 = 4 \det(M)$

We need  $\gamma_1$  &  $\gamma_2$  as 2 linearly independent solutions to  $\gamma' = M\gamma$ .

In this case, since  $d_1 = d_2$ , we need to look at the eigenvectors  $\zeta_1$  &  $\zeta_2$ .

Recall  $d\zeta = M\zeta$ .

\* 2 linearly independent eigenvectors  $\zeta_1$  &  $\zeta_2$ , then we have a star.

$\text{Tr}(M) < 0$  stable star

$\text{Tr}(M) > 0$  unstable star

What if one of the roots is 0 :

$$\det(M) = 0 \quad \lambda_1 = 0 ; \lambda_2 = \text{Tr}(M) \in \mathbb{R}$$

$$Y(t) = C_1 e^{\lambda_1 t} \gamma_1 + C_2 e^{\lambda_2 t} \gamma_2$$

$$= C_1 \gamma_1 + C_2 e^{\lambda_2 t} \gamma_2$$

Choose  $C_2 = 0$  : we have a line of fixed points!